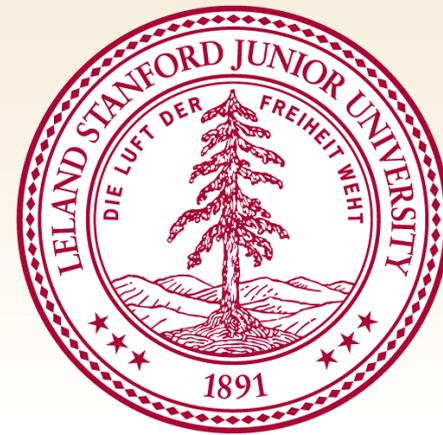


# On The Fundamental Limits of Adaptive Sensing

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# Compressive Sensing

The diagram illustrates the compressive sensing equation  $y = Ax + z$ . On the left, a vertical vector  $y$  is shown with 8 colored cells (green, yellow, blue, orange, red, light green, blue, cyan). This is followed by an equals sign. In the center is a matrix  $A$  of size  $m \times n$ , represented as an 8x12 grid of colored cells. Below the matrix are the labels  $m \times n$  and  $m \ll n$ . To the right of the matrix is a vertical vector  $x$  of size  $n \times 1$ , which is  $k$ -sparse, meaning it has only a few non-zero entries (one yellow, one green, one red, one blue cell). Below the vector  $x$  are the labels  $n \times 1$  and  $k$ -sparse. To the right of the vector  $x$  is a plus sign, followed by a vertical vector  $z$  of size  $m \times 1$  with 8 colored cells (yellow, red, light green, orange, red, cyan, orange, red).

When (and how well) can we estimate  $x$  from the measurements  $y$ ?

# How Well Can We Estimate $x$ ?

$$y = Ax + z \quad z \sim \mathcal{N}(0, \sigma^2 I)$$

Suppose that  $A$  has unit-norm rows.

There exist matrices  $A$  such that for any  $x$  with  $\|x\|_0 \leq k$

$$\mathbb{E} \|\hat{x} - x\|_2^2 \leq C \frac{n}{m} k \sigma^2 \log n.$$

For *any* choice of  $A$  and *any* possible recovery algorithm, there exists an  $x$  with  $\|x\|_0 \leq k$  such that

$$\mathbb{E} \|\hat{x} - x\|_2^2 \geq C' \frac{n}{m} k \sigma^2 \log(n/k).$$

# Room For Improvement?

$$y_i = \langle a_i, x \rangle + z_i$$

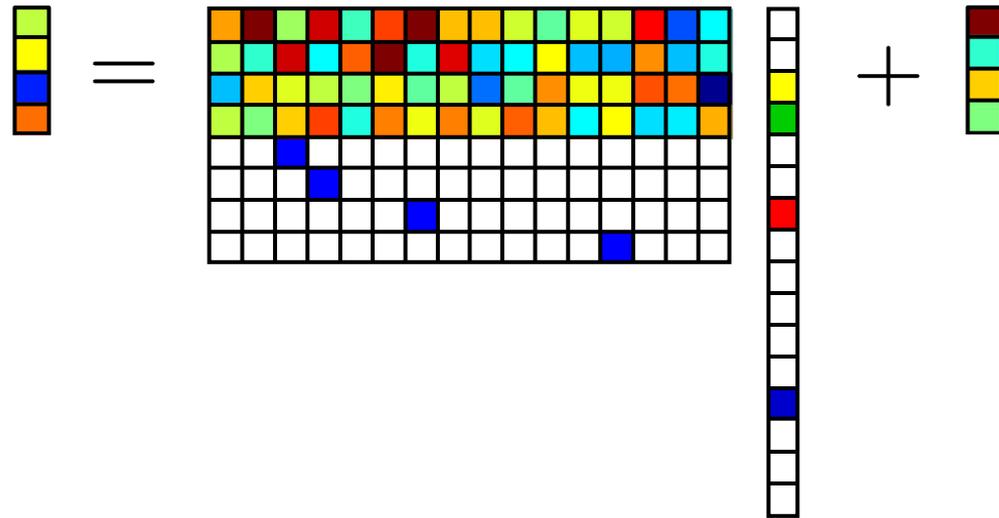


$a_i$  and  $x$  are almost orthogonal

- We are using most of our “sensing power” to sense entries that aren’t even there!
- Tremendous loss in signal-to-noise ratio (SNR)
- It’s hard to imagine any way to avoid this...

# Adaptive Sensing

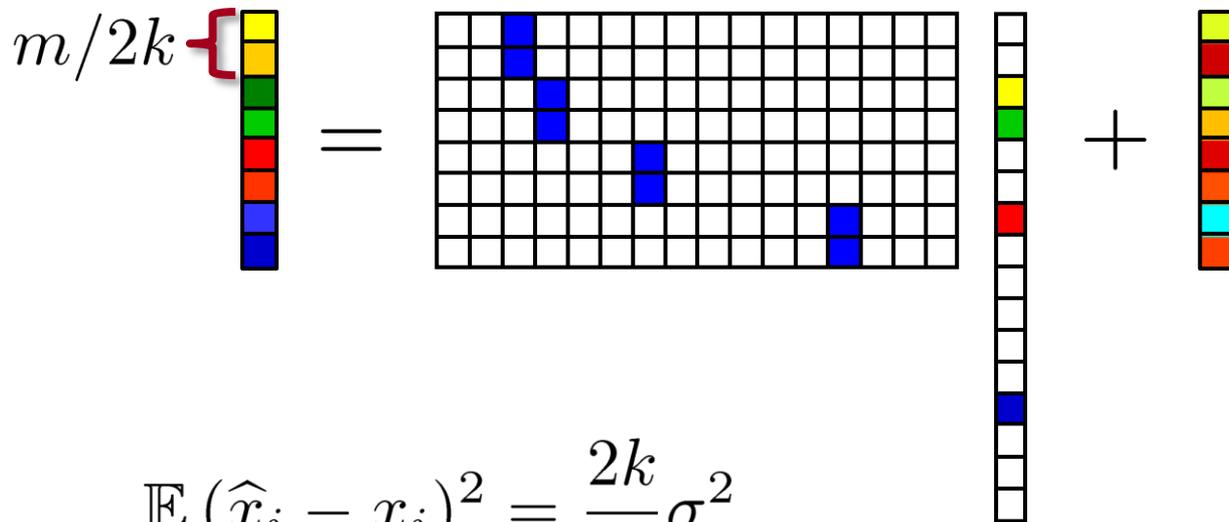
Think of sensing as a game of 20 questions



Simple strategy: Use  $m/2$  measurements to find the support, and the remainder to estimate the values.

# Thought Experiment

Suppose that after  $m/2$  measurements we have perfectly estimated the support.



$$\mathbb{E} (\hat{x}_i - x_i)^2 = \frac{2k}{m} \sigma^2$$

$$\mathbb{E} \|\hat{x} - x\|_2^2 = \frac{2k}{m} k \sigma^2 \ll \frac{n}{m} k \sigma^2 \log n$$

# Does Adaptivity *Really* Help?

Sometimes...

- Noise-free measurements, but non-sparse signal
  - adaptivity doesn't help if you want a uniform guarantee
  - probabilistic adaptive algorithms can reduce the required number of measurements from  $O(k \log(n/k))$  to  $O(k \log \log(n/k))$  [Indyk et al. - 2011]
- Noisy setting
  - distilled sensing [Haupt et al. - 2007, 2010]
  - adaptivity can reduce the estimation error to

$$\mathbb{E} \|\hat{x} - x\|_2^2 = \frac{n}{m} k \sigma^2$$

$$\mathbb{E} \|\hat{x} - x\|_2^2 = \frac{k}{m} k \sigma^2$$

*Which is it?*



# Which Is It?

Suppose we have a budget of  $m$  measurements of the form  $y_i = \langle a_i, x \rangle + z_i$  where  $\|a_i\|_2 = 1$  and  $z_i \sim \mathcal{N}(0, \sigma^2)$

The vector  $a_i$  can have an arbitrary dependence on the measurement history, i.e.,  $(a_1, y_1), \dots, (a_{i-1}, y_{i-1})$

## Theorem

There exist  $x$  with  $\|x\|_0 \leq k$  such that for *any* adaptive measurement strategy and *any* recovery procedure  $\hat{x}$ ,

$$\mathbb{E} \|\hat{x}(y) - x\|_2^2 \geq C \frac{n}{m} k \sigma^2.$$

Thus, in general, adaptivity does *not* significantly help!

# Proof Strategy

**Step 1:** Consider sparse signals with nonzeros of amplitude

$$\mu \approx \sigma \sqrt{n/m}$$

**Step 2:** Show that if given a budget of  $m$  measurements, you cannot detect the support very well

**Step 3:** Immediately translate this into a lower bound on the MSE

To make things simpler, we will consider a Bernoulli prior  $\pi(x)$  instead of a uniform  $k$ -sparse prior:

$$x_j = \begin{cases} 0 & \text{with probability } 1 - k/n \\ \mu > 0 & \text{with probability } k/n \end{cases}$$

# Proof of Main Result

Let  $S = \{j : x_j \neq 0\}$  and set  $\sigma^2 = 1$

For any estimator  $\hat{x}$ , define  $\hat{S} := \{j : |\hat{x}_j| \geq \mu/2\}$

Whenever  $j \in S \setminus \hat{S}$  or  $j \in \hat{S} \setminus S$ ,  $|\hat{x}_j - x_j| \geq \mu/2$

$$\|\hat{x} - x\|_2^2 \geq \frac{\mu^2}{4} |S \setminus \hat{S}| + \frac{\mu^2}{4} |\hat{S} \setminus S| = \frac{\mu^2}{4} |\hat{S} \Delta S|$$


$$\mathbb{E} \|\hat{x} - x\|_2^2 \geq \frac{\mu^2}{4} \mathbb{E} |\hat{S} \Delta S|$$

# Proof of Main Result

## Lemma

Under the Bernoulli prior, *any* estimate  $\hat{S}$  satisfies

$$\mathbb{E} |\hat{S} \Delta S| \geq k \left( 1 - \frac{\mu}{2} \sqrt{\frac{m}{n}} \right).$$

Thus, 
$$\begin{aligned} \mathbb{E} \|\hat{x} - x\|_2^2 &\geq \frac{\mu^2}{4} \mathbb{E} |\hat{S} \Delta S| \\ &\geq k \cdot \frac{\mu^2}{4} \left( 1 - \frac{\mu}{2} \sqrt{\frac{m}{n}} \right) \end{aligned}$$

Plug in  $\mu = \frac{8}{3} \sqrt{\frac{n}{m}}$  and this reduces to

$$\mathbb{E} \|\hat{x} - x\|_2^2 \geq \frac{4}{27} \cdot \frac{kn}{m} \geq \frac{1}{7} \cdot \frac{kn}{m}$$

# Key Ideas in Proof of Lemma

$$\mathbb{P}_{0,j}(y_1, \dots, y_m) = \mathbb{P}(y_1, \dots, y_m | x_j = 0)$$

$$\mathbb{P}_{1,j}(y_1, \dots, y_m) = \mathbb{P}(y_1, \dots, y_m | x_j = \mu)$$

$$\begin{aligned} \mathbb{E} |\widehat{S} \Delta S| &\geq \frac{k}{n} \sum_j (1 - \|\mathbb{P}_{1,j} - \mathbb{P}_{0,j}\|_{\text{TV}}) \\ &\geq k - \frac{k}{\sqrt{n}} \sqrt{\sum_j \|\mathbb{P}_{1,j} - \mathbb{P}_{0,j}\|_{\text{TV}}^2} \end{aligned}$$

$$\sum_j \|\mathbb{P}_{1,j} - \mathbb{P}_{0,j}\|_{\text{TV}}^2 \leq \frac{\mu^2}{4} m \quad \longrightarrow \quad \mathbb{E} |\widehat{S} \Delta S| \geq k \left( 1 - \frac{\mu}{2} \sqrt{\frac{m}{n}} \right)$$

# Key Ideas in Proof of Lemma

## Pinsker's Inequality

$$\|\mathbb{P} - \mathbb{Q}\|_{\text{TV}} \leq \sqrt{K(\mathbb{P}, \mathbb{Q})/2}$$

$$\begin{aligned} \|\mathbb{P}_{1,j} - \mathbb{P}_{0,j}\|_{\text{TV}}^2 &\leq \frac{\pi_0}{2} K(\mathbb{P}_{0,j}, \mathbb{P}_{1,j}) + \frac{\pi_1}{2} K(\mathbb{P}_{1,j}, \mathbb{P}_{0,j}) \\ &\leq \frac{\mu^2}{4} \sum_i \mathbb{E} a_{i,j}^2 \end{aligned}$$

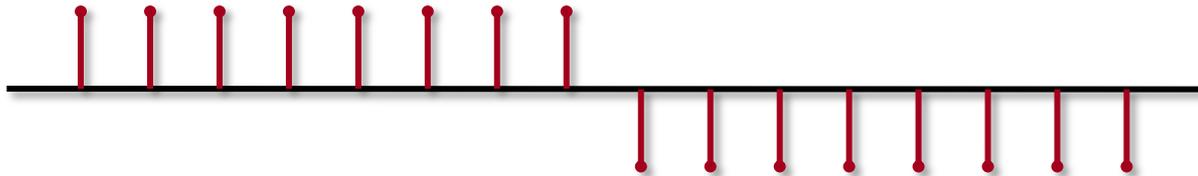

$$\sum_j \|\mathbb{P}_{1,j} - \mathbb{P}_{0,j}\|_{\text{TV}}^2 \leq \frac{\mu^2}{4} \sum_{i,j} \mathbb{E} a_{i,j}^2 = \frac{\mu^2}{4} m$$

# Adaptivity In Practice

Suppose that  $k = 1$  and that  $x_{j^*} = \mu$

Binary Search [Iwen and Tewfik - 2011, Davenport and Arias-Castro - 2012]

- split measurements into  $\log n$  stages
- in each stage, use measurements to decide if the nonzero is in the left or right half of the “active set”
- after subdividing  $\log n$  times, return support

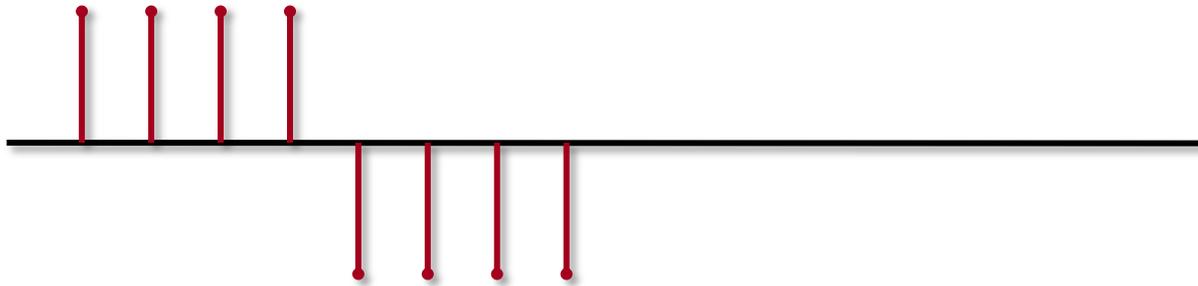


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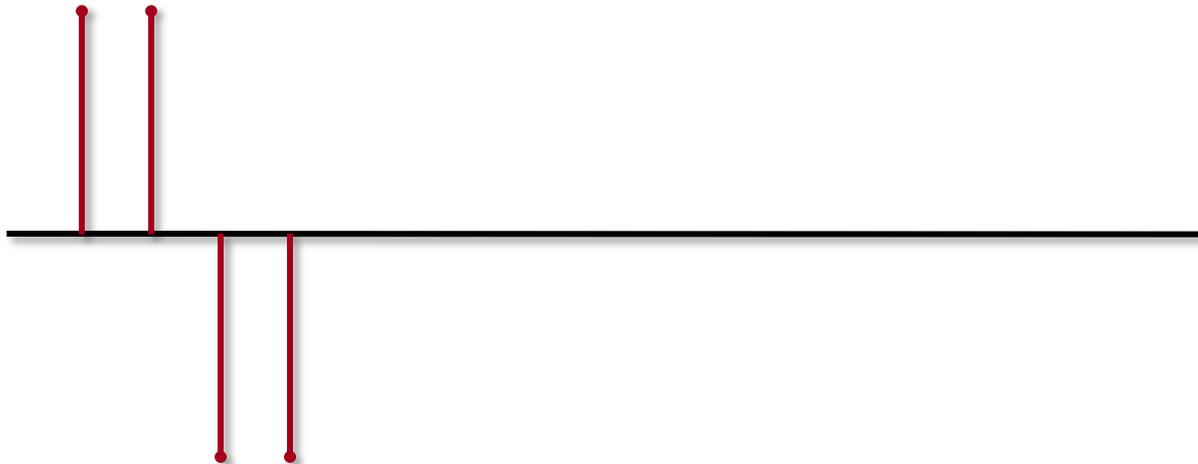


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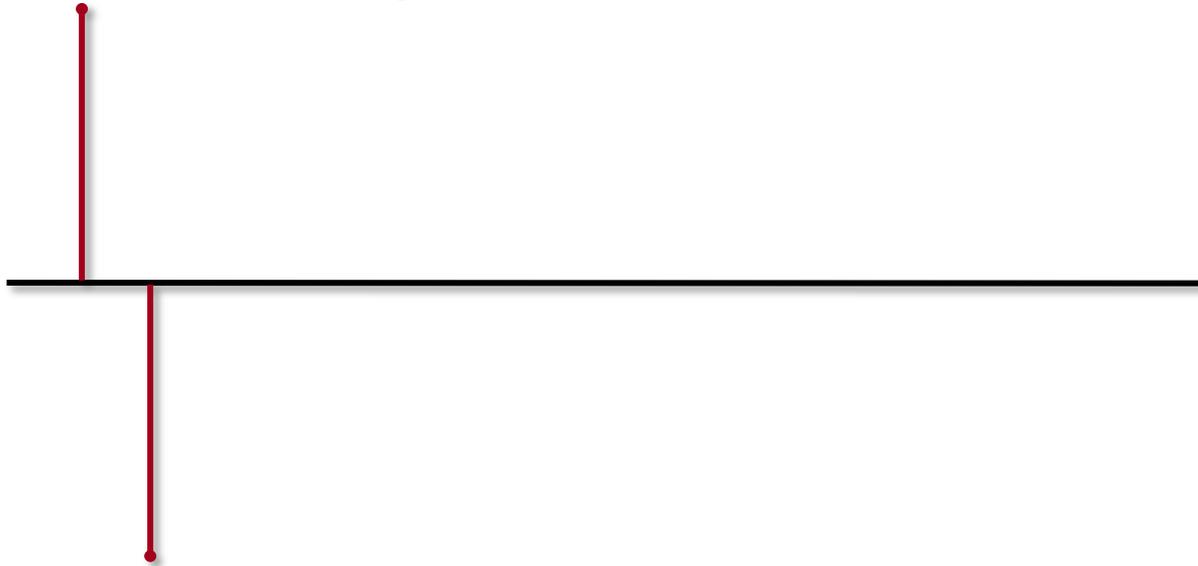


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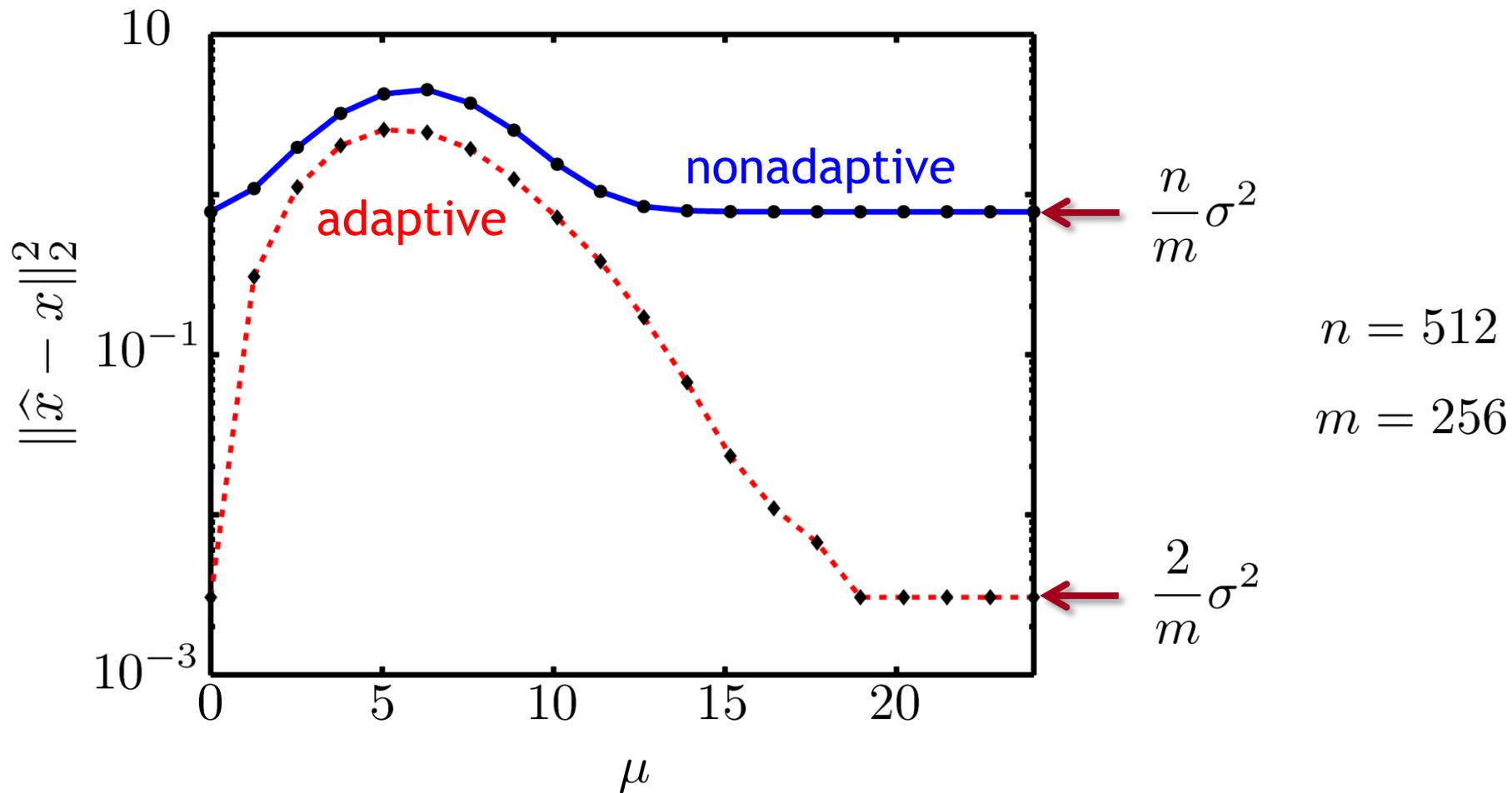
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# Experimental Results



# Conclusions

- Surprisingly, adaptive algorithms, no matter how complex, cannot in general significantly improve over seemingly naively simple nonadaptive strategies
- Adaptivity might still be very useful in practice
  - how large does  $\mu$  need to be to transition from the regime where adaptivity doesn't help to where it does?

$$\frac{\mu}{\sigma} \geq C \sqrt{(n/m) \log \log n}$$

- improved practical algorithms that work well simultaneously for both large and small values of  $\mu$
- practical architectures and algorithms for implementing adaptive measurements in real-world settings