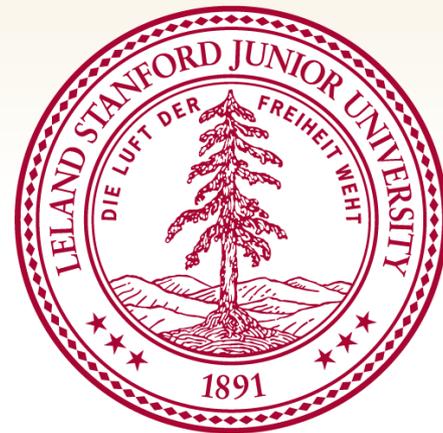


To Adapt or Not To Adapt

The Power and Limits of Adaptive Sensing

Mark A. Davenport

Stanford University
Department of Statistics



Compressive Sensing

$y = Ax + z$

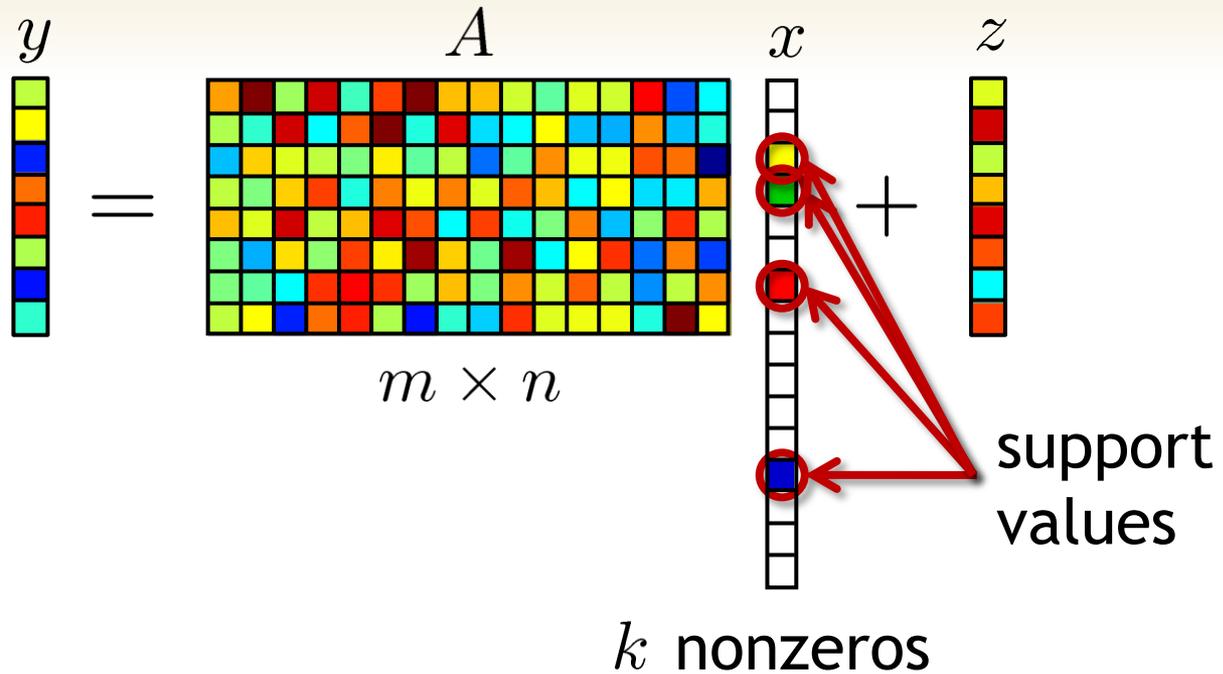
$m \times n$
 $m \ll n$

$n \times 1$
 k -sparse

When (and how well) can we estimate x from the measurements y ?

Review of Nonadaptive Compressive Sensing

Compressive Sensing



- How should we design A to ensure that y contains as much information about x as possible?
- What algorithms do we have for recovering x from y ?

How To Design A ?

Prototypical sensing model:

$$y = Ax + z \quad z \sim \mathcal{N}(0, \sigma^2 I)$$

- Constrain A to have unit-norm rows
- Pick A at *random!*
 - i.i.d. Gaussian entries (with variance $1/n$)
 - random rows from a unitary matrix
- As long as $m = O(k \log(n/k))$, with high probability a random A will satisfy the *restricted isometry property*
- Deep connections with *Johnson-Lindenstrauss Lemma*
 - see Baraniuk, Davenport, DeVore, and Wakin (2008)

How To Recover x ?

- Lots and lots of algorithms
 - ℓ_1 -minimization
 - greedy algorithms (matching pursuit, CoSaMP, IHT)

If A satisfies the RIP, $\|x\|_0 \leq k$, and $y = Ax + z$ with $z \sim \mathcal{N}(0, \sigma^2 I)$, then

$$\hat{x} = \arg \min_{x' \in \mathbb{R}^n} \|x'\|_1$$

$$\text{s.t. } \|A^*(y - Ax')\|_\infty \leq c\sqrt{\log n}\sigma$$

satisfies

$$\mathbb{E} \|\hat{x} - x\|_2^2 \leq C \frac{n}{m} k \sigma^2 \log n.$$

[Candès and Tao - 2005]

Room For Improvement?

There exists matrices A such that for *any* (sparse) x we have

$$\mathbb{E} \|\hat{x} - x\|_2^2 \leq C \frac{n}{m} k \sigma^2 \log n.$$

$$y_i = \langle a_i, x \rangle + z_i$$



a_i and x are almost orthogonal

- We are using most of our “sensing power” to sense entries that aren’t even there!
- Tremendous loss in signal-to-noise ratio (SNR)
- It’s hard to imagine any way to avoid this...

Can We Do Better?

Theorem

For *any* matrix A (with unit-norm rows) and *any* recovery procedure \hat{x} , there exists an x with $\|x\|_0 \leq k$ such that if $y = Ax + z$ with $z \sim \mathcal{N}(0, \sigma^2 I)$, then

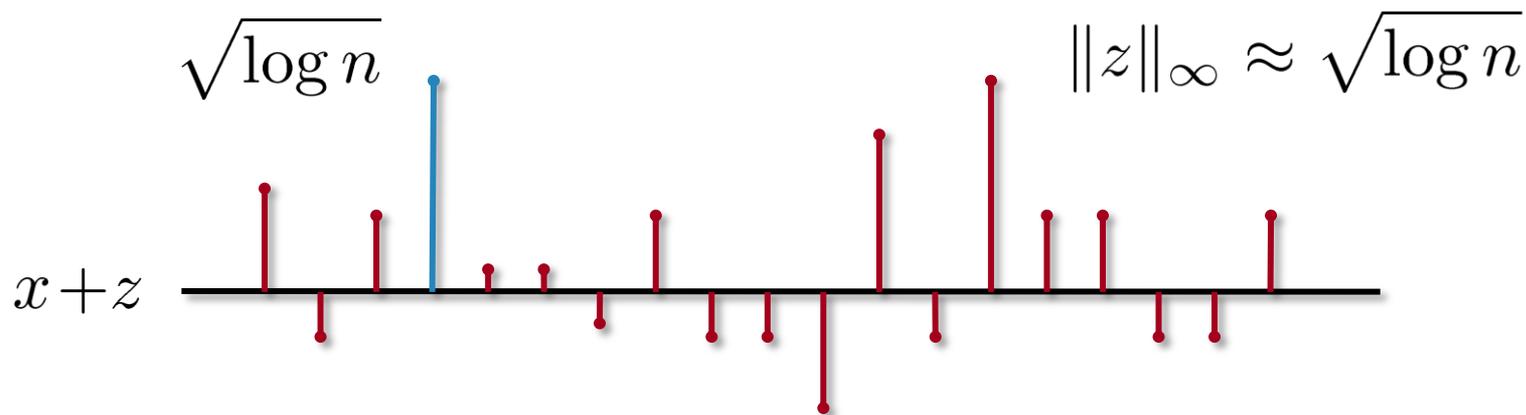
$$\mathbb{E} \|\hat{x}(y) - x\|_2^2 \geq C' \frac{n}{m} k \sigma^2 \log(n/k).$$

Compressive sensing is already operating at the limit

Intuition

Suppose that $y = x + z$ with $z \sim \mathcal{N}(0, I)$ and that $k = 1$

$$\mathbb{E} \|\hat{x}(y) - x\|_2^2 \geq C' \log n$$



Proof Recipe

Ingredients (Makes $\sigma^2 = 1$ servings)

- Lemma 1: There exists a set \mathcal{X} of k -sparse vectors such that
 - $|\mathcal{X}| = (n/k)^{k/4}$
 - $\|x_i - x_j\|_2 \geq \frac{1}{2}$ for all $x_i, x_j \in \mathcal{X}$
 - $\left\| \frac{1}{|\mathcal{X}|} \sum_i x_i x_i^* - \frac{1}{n} I \right\| \leq \frac{\beta}{n}$ for some $\beta > 0$
- Lemma 2: Define $R_{\text{mm}}^*(A) = \inf_{\hat{x}} \sup_{\|x\|_0 \leq k} \mathbb{E} [\|\hat{x}(Ax + z) - x\|_2^2]$.
Suppose \mathcal{X} is a set of k -sparse vectors such that $\|x_i - x_j\|_2^2 \geq 8nR_{\text{mm}}^*(A)$ for all $x_i, x_j \in \mathcal{X}$.
Then $\frac{1}{2} \log |\mathcal{X}| - 1 \leq \frac{1}{2|\mathcal{X}|^2} \sum_{i,j} \|Ax_i - Ax_j\|_2^2$.

Instructions

Combine ingredients and add a dash of linear algebra.

The Details

$$\mu = \frac{1}{|\mathcal{X}|} \sum_i x_i \quad Q = \frac{1}{|\mathcal{X}|} \sum_i x_i x_i^*$$

$$\begin{aligned} \frac{k}{4} \log(n/k) - 2 &\leq \frac{1}{|\mathcal{X}|^2} \sum_{i,j} \|Ax_i - Ax_j\|_2^2 \\ &= \text{Tr} \left(A^* A \left(\frac{1}{|\mathcal{X}|^2} \sum_{i,j} (x_i - x_j)(x_i - x_j)^* \right) \right) \\ &= \text{Tr} (A^* A (2(Q - \mu\mu^*))) \\ &\leq 2\text{Tr} (A^* A Q) \\ &\leq 2\text{Tr} (A^* A) \|Q\| \\ &\leq 2\|A\|_F^2 \cdot 16R_{\text{mm}}^*(A)(1 + \beta) \end{aligned}$$


$$R_{\text{mm}}^*(A) \geq \frac{k \log(n/k)}{128(1 + \beta)\|A\|_F^2}$$

Lemma 1

Lemma 1: There exists a set \mathcal{X} of k -sparse points such that

- $|\mathcal{X}| = (n/k)^{k/4}$
- $\|x_i - x_j\|_2 \geq \frac{1}{2}$ for all $x_i, x_j \in \mathcal{X}$
- $\left\| \frac{1}{|\mathcal{X}|} \sum_i x_i x_i^* - \frac{1}{n} I \right\| \leq \frac{\beta}{n}$ for some $\beta > 0$

Strategy

Construct \mathcal{X} by sampling (with replacement) from

$$\mathcal{U} = \left\{ x \in \{0, \sqrt{1/k}, -\sqrt{1/k}\}^n : \|x\|_0 \leq k \right\}$$

Repeat for $|\mathcal{X}| = (n/k)^{k/4}$ iterations.

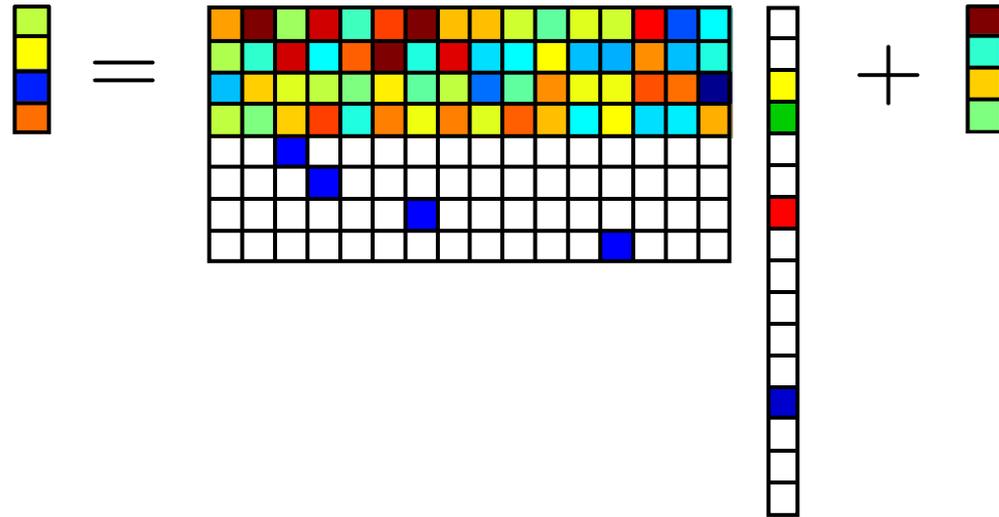
With probability > 0 , the remaining properties are satisfied.

Key: Matrix Bernstein Inequality [Ahlsvede and Winter, 2002]

Adaptive Sensing

Adaptive Sensing

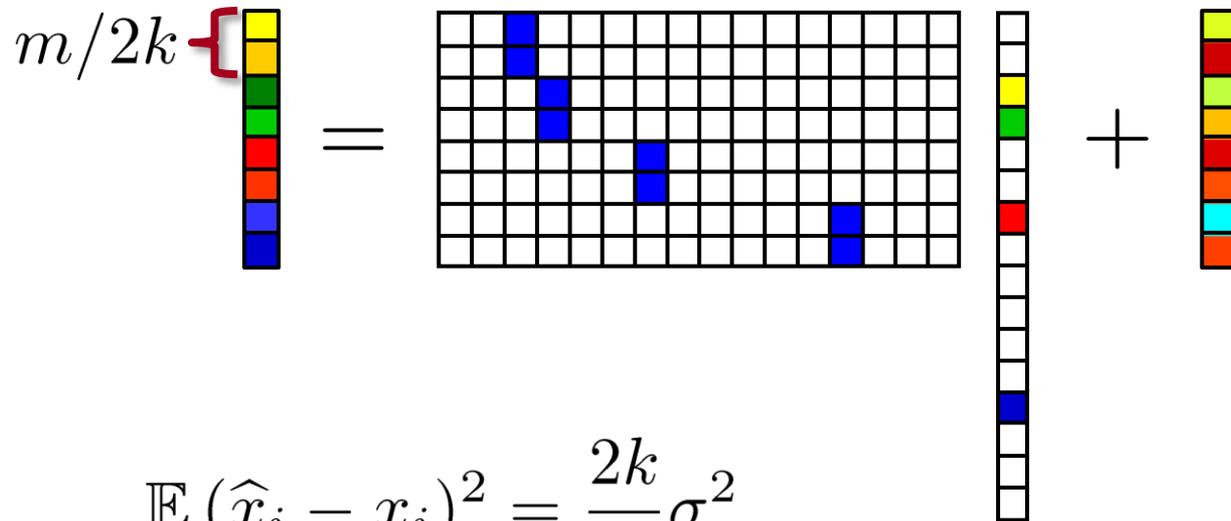
Think of sensing as a game of 20 questions



Simple strategy: Use $m/2$ measurements to find the support, and the remainder to estimate the values.

Thought Experiment

Suppose that after $m/2$ measurements we have perfectly estimated the support.



$$\mathbb{E} (\hat{x}_i - x_i)^2 = \frac{2k}{m} \sigma^2$$

$$\mathbb{E} \|\hat{x} - x\|_2^2 = \frac{2k}{m} k \sigma^2 \ll \frac{n}{m} k \sigma^2 \log n$$

Does Adaptivity *Really* Help?

Sometimes...

- Noise-free measurements, but non-sparse signal
 - adaptivity doesn't help if you want a uniform guarantee
 - probabilistic adaptive algorithms can reduce the required number of measurements from $O(k \log(n/k))$ to $O(k \log \log(n/k))$ [Indyk et al. - 2011]
- Noisy setting
 - distilled sensing [Haupt et al. - 2007, 2010]
 - adaptivity can reduce the estimation error to

$$\mathbb{E} \|\hat{x} - x\|_2^2 = \frac{n}{m} k \sigma^2$$

$$\mathbb{E} \|\hat{x} - x\|_2^2 = \frac{k}{m} k \sigma^2$$

Which is it?



Which Is It?

Suppose we have a budget of m measurements of the form $y_i = \langle a_i, x \rangle + z_i$ where $\|a_i\|_2 = 1$ and $z_i \sim \mathcal{N}(0, \sigma^2)$

The vector a_i can have an arbitrary dependence on the measurement history, i.e., $(a_1, y_1), \dots, (a_{i-1}, y_{i-1})$

Theorem

There exist x with $\|x\|_0 \leq k$ such that for *any* adaptive measurement strategy and *any* recovery procedure \hat{x} ,

$$\mathbb{E} \|\hat{x}(y) - x\|_2^2 \geq C \frac{n}{m} k \sigma^2.$$

Thus, in general, adaptivity does *not* significantly help!

Proof Strategy

- Step 1:** Consider a prior on sparse signals with nonzeros of amplitude $\mu \approx \sigma \sqrt{n/m}$
- Step 2:** Show that if given a budget of m measurements, you cannot detect the support very well
- Step 3:** Immediately translate this into a lower bound on the MSE

To make things simpler, we will consider a Bernoulli prior $\pi(x)$ instead of a uniform k -sparse prior:

$$x_j = \begin{cases} 0 & \text{with probability } 1 - k/n \\ \mu > 0 & \text{with probability } k/n \end{cases}$$

Proof of Main Result

Let $S = \{j : x_j \neq 0\}$ and set $\sigma^2 = 1$

For any estimator \hat{x} , define $\hat{S} := \{j : |\hat{x}_j| \geq \mu/2\}$

Whenever $j \in S \setminus \hat{S}$ or $j \in \hat{S} \setminus S$, $|\hat{x}_j - x_j| \geq \mu/2$

$$\|\hat{x} - x\|_2^2 \geq \frac{\mu^2}{4} |S \setminus \hat{S}| + \frac{\mu^2}{4} |\hat{S} \setminus S| = \frac{\mu^2}{4} |\hat{S} \Delta S|$$


$$\mathbb{E} \|\hat{x} - x\|_2^2 \geq \frac{\mu^2}{4} \mathbb{E} |\hat{S} \Delta S|$$

Proof of Main Result

Lemma

Under the Bernoulli prior, *any* estimate \hat{S} satisfies

$$\mathbb{E} |\hat{S} \Delta S| \geq k \left(1 - \frac{\mu}{2} \sqrt{\frac{m}{n}} \right).$$

Thus,
$$\begin{aligned} \mathbb{E} \|\hat{x} - x\|_2^2 &\geq \frac{\mu^2}{4} \mathbb{E} |\hat{S} \Delta S| \\ &\geq k \cdot \frac{\mu^2}{4} \left(1 - \frac{\mu}{2} \sqrt{\frac{m}{n}} \right) \end{aligned}$$

Plug in $\mu = \frac{8}{3} \sqrt{\frac{n}{m}}$ and this reduces to

$$\mathbb{E} \|\hat{x} - x\|_2^2 \geq \frac{4}{27} \cdot \frac{kn}{m} \geq \frac{1}{7} \cdot \frac{kn}{m}$$

Key Ideas in Proof of Lemma

$$\mathbb{P}_{0,j}(y_1, \dots, y_m) = \mathbb{P}(y_1, \dots, y_m | x_j = 0)$$

$$\mathbb{P}_{1,j}(y_1, \dots, y_m) = \mathbb{P}(y_1, \dots, y_m | x_j = \mu)$$

$$\begin{aligned} \mathbb{E} |\widehat{S} \Delta S| &\geq \frac{k}{n} \sum_j (1 - \|\mathbb{P}_{1,j} - \mathbb{P}_{0,j}\|_{\text{TV}}) \\ &\geq k - \frac{k}{\sqrt{n}} \sqrt{\sum_j \|\mathbb{P}_{1,j} - \mathbb{P}_{0,j}\|_{\text{TV}}^2} \end{aligned}$$

$$\sum_j \|\mathbb{P}_{1,j} - \mathbb{P}_{0,j}\|_{\text{TV}}^2 \leq \frac{\mu^2}{4} m \quad \longrightarrow \quad \mathbb{E} |\widehat{S} \Delta S| \geq k \left(1 - \frac{\mu}{2} \sqrt{\frac{m}{n}} \right)$$

Key Ideas in Proof of Lemma

Pinsker's Inequality

$$\|\mathbb{P} - \mathbb{Q}\|_{\text{TV}} \leq \sqrt{K(\mathbb{P}, \mathbb{Q})/2}$$

$$\begin{aligned} \|\mathbb{P}_{1,j} - \mathbb{P}_{0,j}\|_{\text{TV}}^2 &\leq \frac{\pi_0}{2} K(\mathbb{P}_{0,j}, \mathbb{P}_{1,j}) + \frac{\pi_1}{2} K(\mathbb{P}_{1,j}, \mathbb{P}_{0,j}) \\ &\leq \frac{\mu^2}{4} \sum_i \mathbb{E} a_{i,j}^2 \end{aligned}$$


$$\sum_j \|\mathbb{P}_{1,j} - \mathbb{P}_{0,j}\|_{\text{TV}}^2 \leq \frac{\mu^2}{4} \sum_{i,j} \mathbb{E} a_{i,j}^2 = \frac{\mu^2}{4} m$$

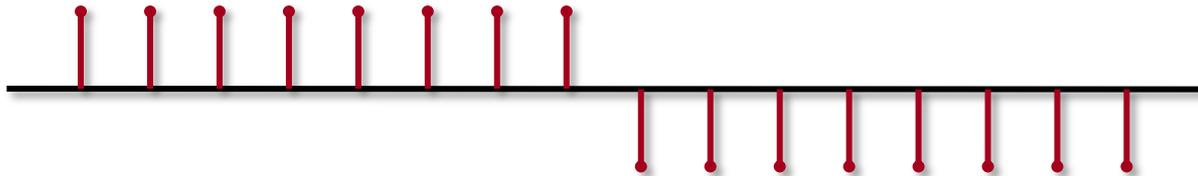
Adaptivity in Practice

Adaptivity In Practice

Suppose that $k = 1$ and that $x_{j^*} = \mu$

Binary Search [Iwen and Tewfik - 2011, Davenport and Arias-Castro - 2012]

- split measurements into $\log n$ stages
- in each stage, use measurements to decide if the nonzero is in the left or right half of the “active set”
- after subdividing $\log n$ times, return support

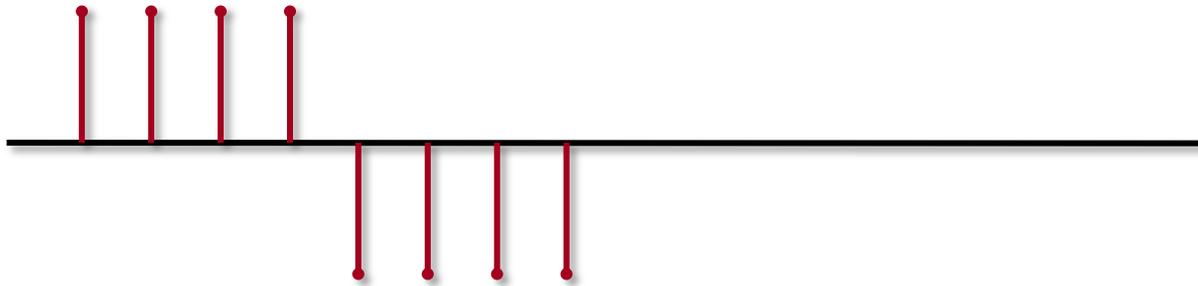


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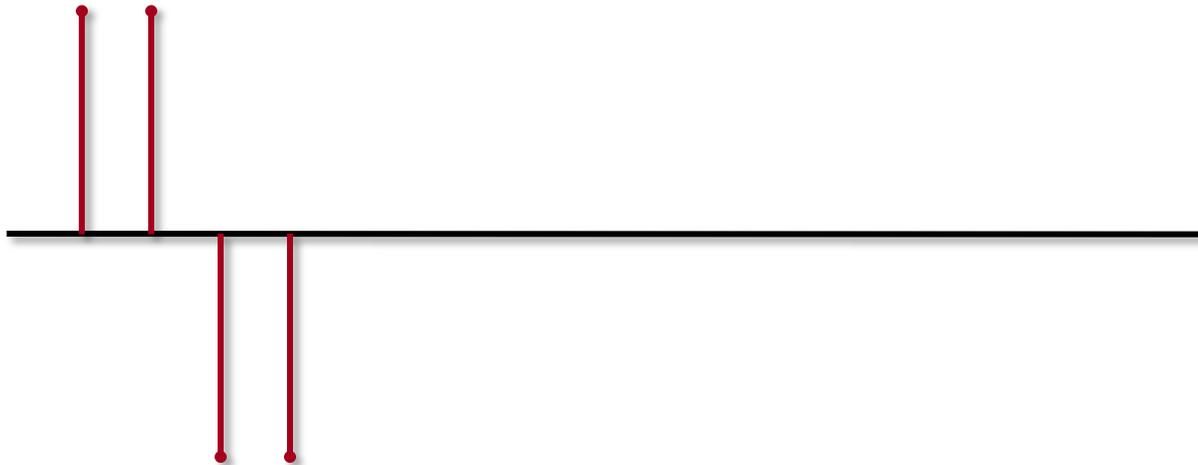


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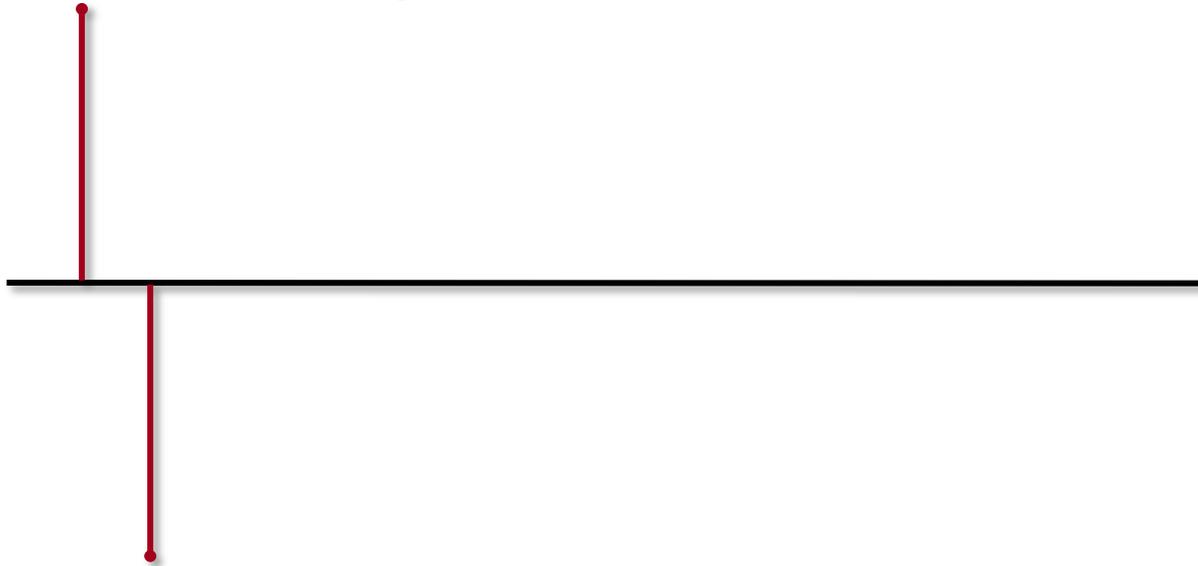


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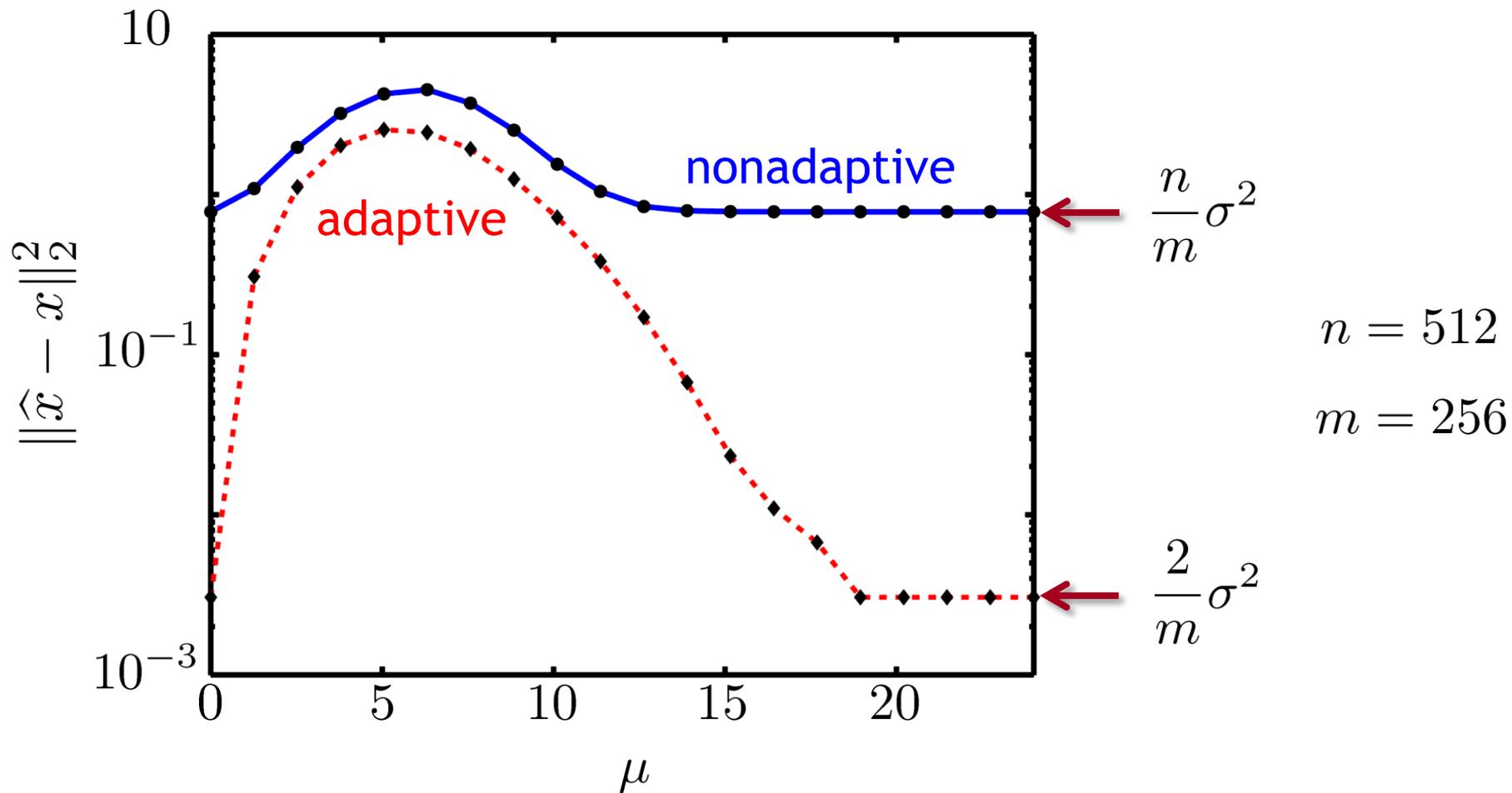
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Experimental Results



Open Questions

- No method can succeed when $\frac{\mu}{\sigma} \approx \sqrt{\frac{n}{m}}$, but the binary search approach succeeds as long as $\frac{\mu}{\sigma} \geq C \sqrt{\frac{n}{m} \log \log n}$
[Davenport and Arias-Castro - 2012]
- Practical algorithms that work well for all values of μ
- Practical algorithms for $k > 1$
- New theory for restricted adaptive measurements
 - single-pixel camera: 0/1 measurements
 - magnetic resonance imaging (MRI): Fourier measurements
 - analog-to-digital converters: linear filter measurements
- New sensors and architectures that can actually acquire adaptive measurements

More Information

<http://stat.stanford.edu/~markad>

markad@stanford.edu