



Compressive Signal Processing

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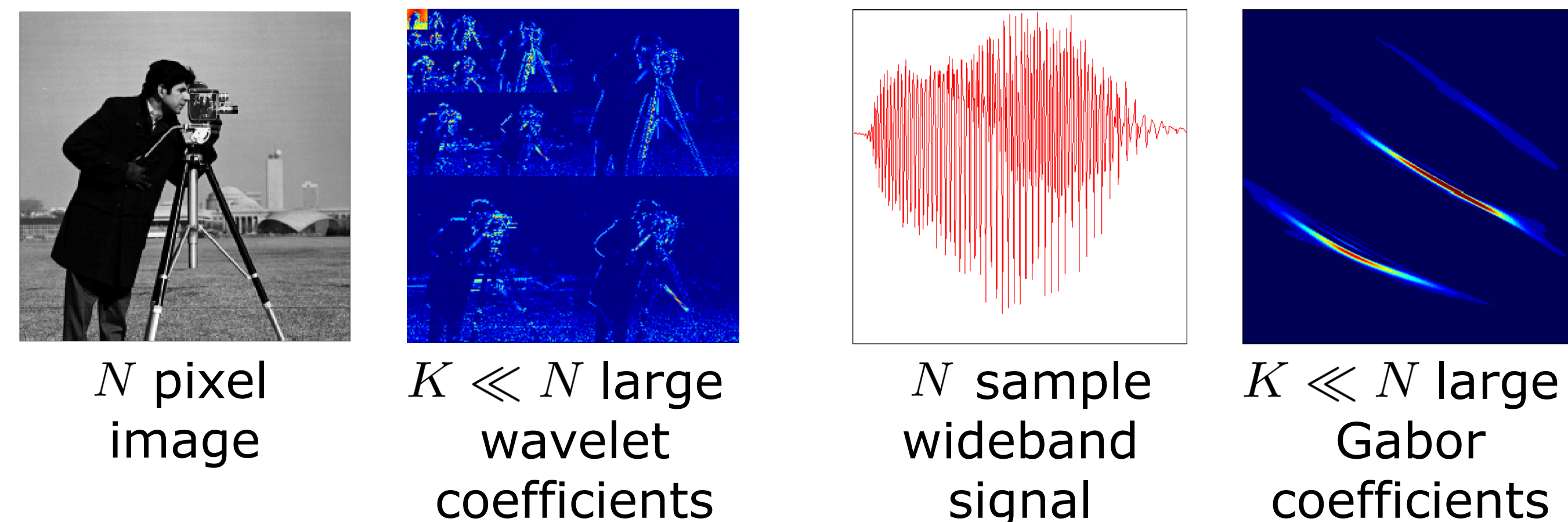
Compressive Sensing

- Natural and man made signals often have **sparse** or **compressible** structure
- Traditional acquisition: sample then compress
- Compressive acquisition: compress and sample together

Compression and Sparsity

Traditional signal acquisition:

- Sample** data at Nyquist rate (2x bandwidth)
- Compress** data (signal dependent, nonlinear)



Compressive Sensing (CS)

- Directly acquire **compressive measurements** – random projections, sketches

$$\begin{matrix} M \times 1 \\ \text{measurements} \end{matrix} \mathbf{y} = \begin{matrix} \Phi \\ M \times N \end{matrix} \begin{matrix} \Psi \\ N \times N \end{matrix} \begin{matrix} \alpha \\ N \times 1 \text{ signal} \\ K \text{ nonzero} \\ \text{coefficients} \end{matrix}$$

$M = O(K \log(N/K)) \ll N$

Signal Recovery

- Recovery is an ill-posed inverse problem
- Successful algorithm must **exploit sparsity** – linear programming

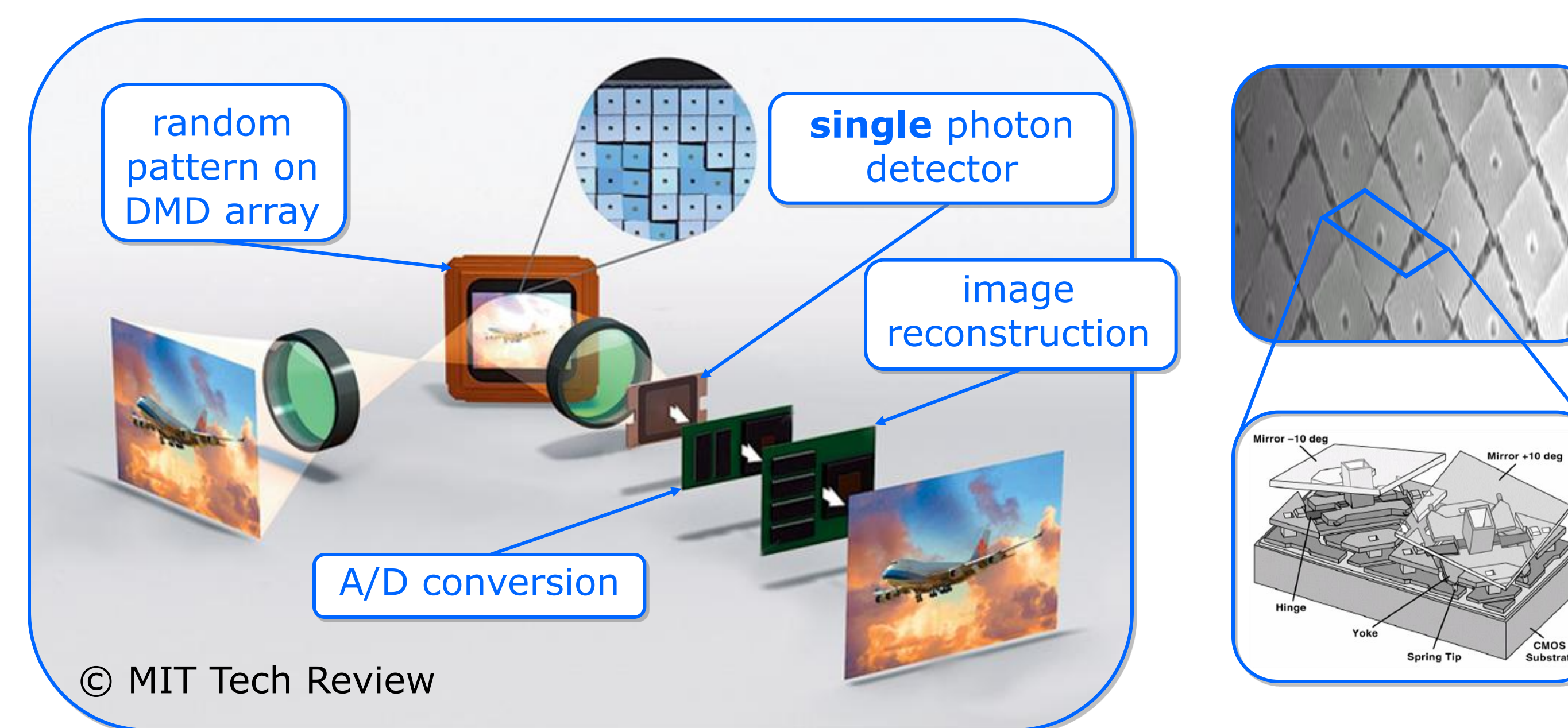
$$\hat{x} = \arg \min_{\|y - \Phi x\|_2 \leq \epsilon} \|x\|_1 \rightarrow \|\hat{x} - x_0\|_2 \leq C \|x^* - x_0\|_2$$

- orthogonal matching pursuit
- heavy-hitters algorithms
- many others

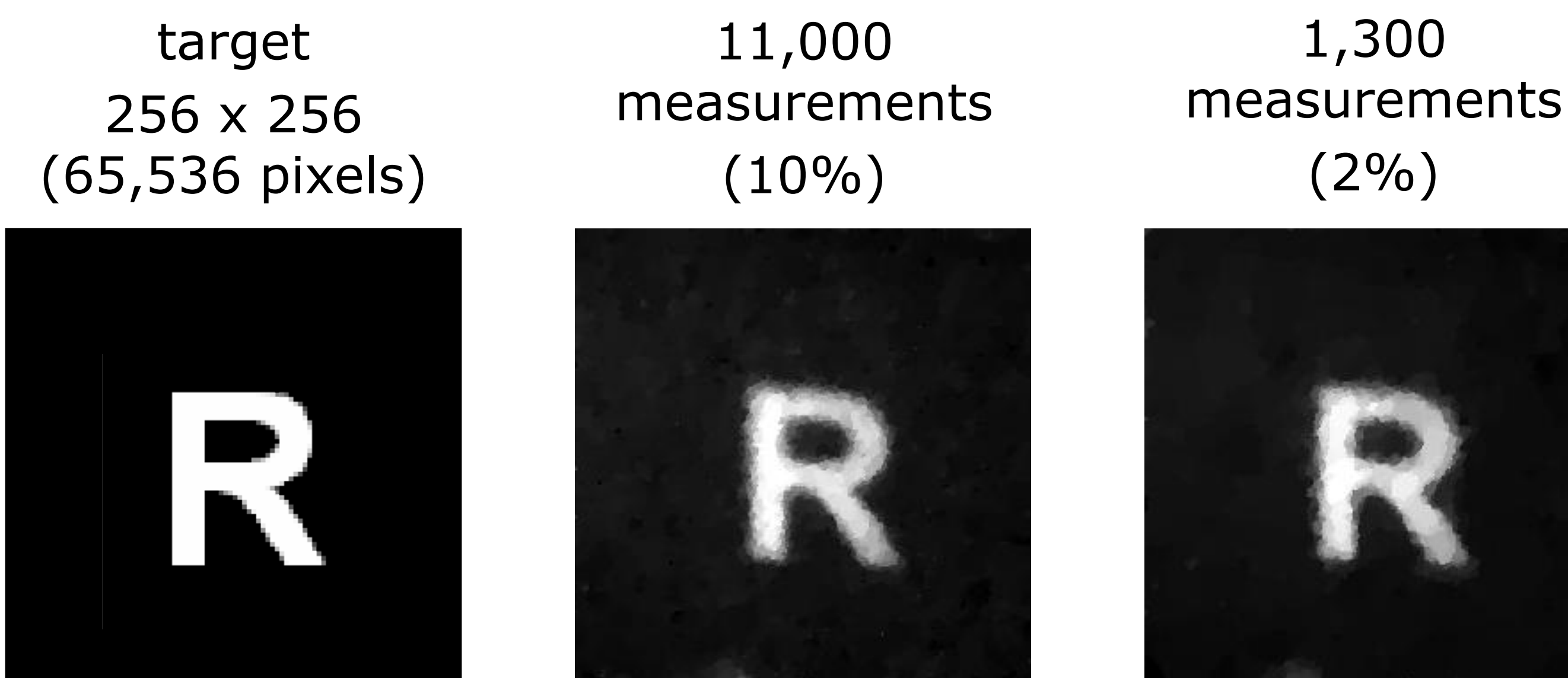
Single-pixel Camera

- Compressive imager uses **DMD** to take **projections** of the image
- Requires only **one photon sensor**
- Low cost, low power, new modalities

Camera Architecture



Early Results



Color, Low-light Imaging



- True color, low-light imaging
- 10:1 compression ratio

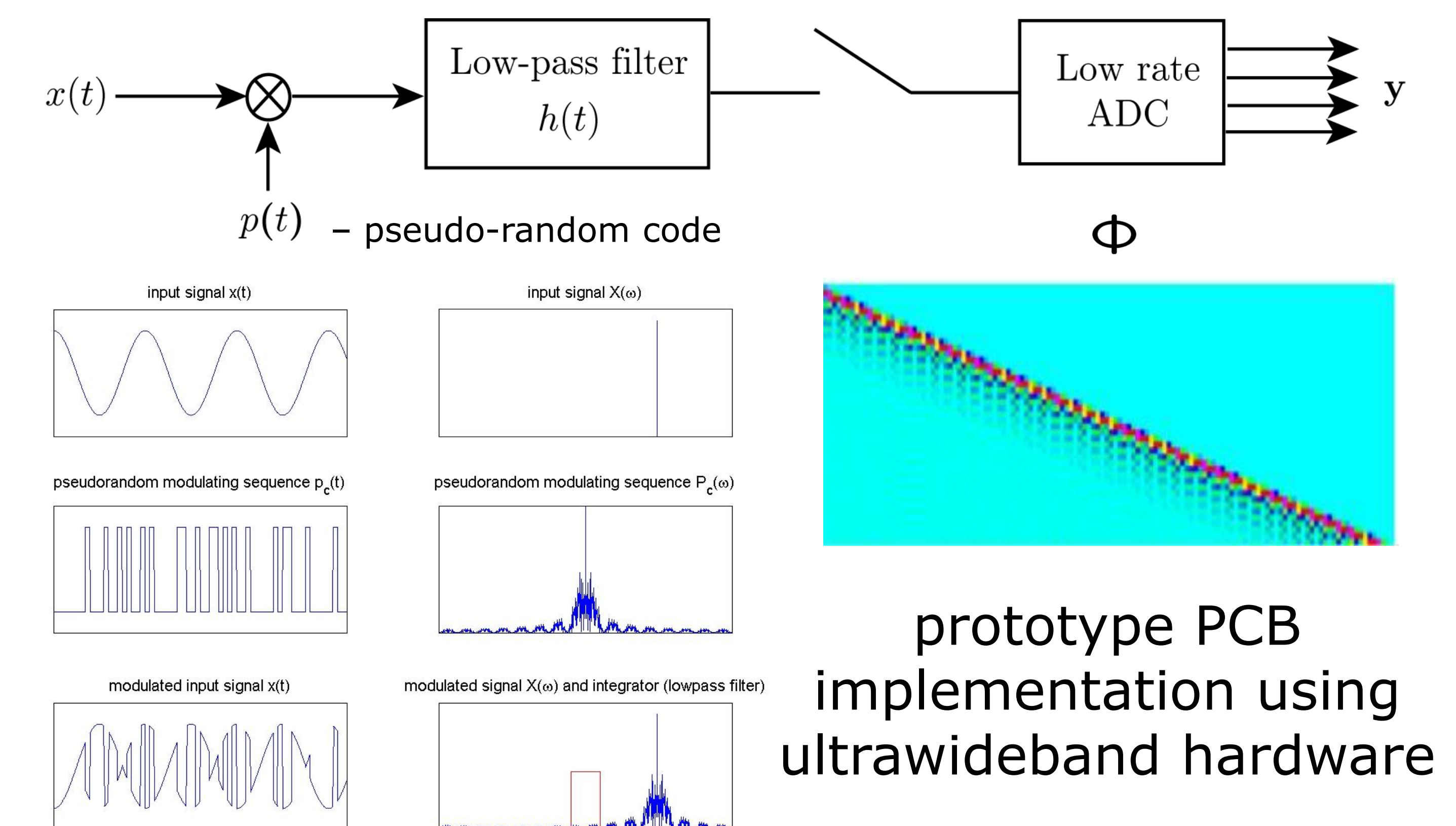


dsp.rice.edu/cs

Analog-to-Information Conversion

- CS enables analog-to-digital conversion at a signal's (potentially low) **information rate** rather than at the (potentially high) **Nyquist rate**
- Smashed filter** for compressive classification

Random Demodulator AIC

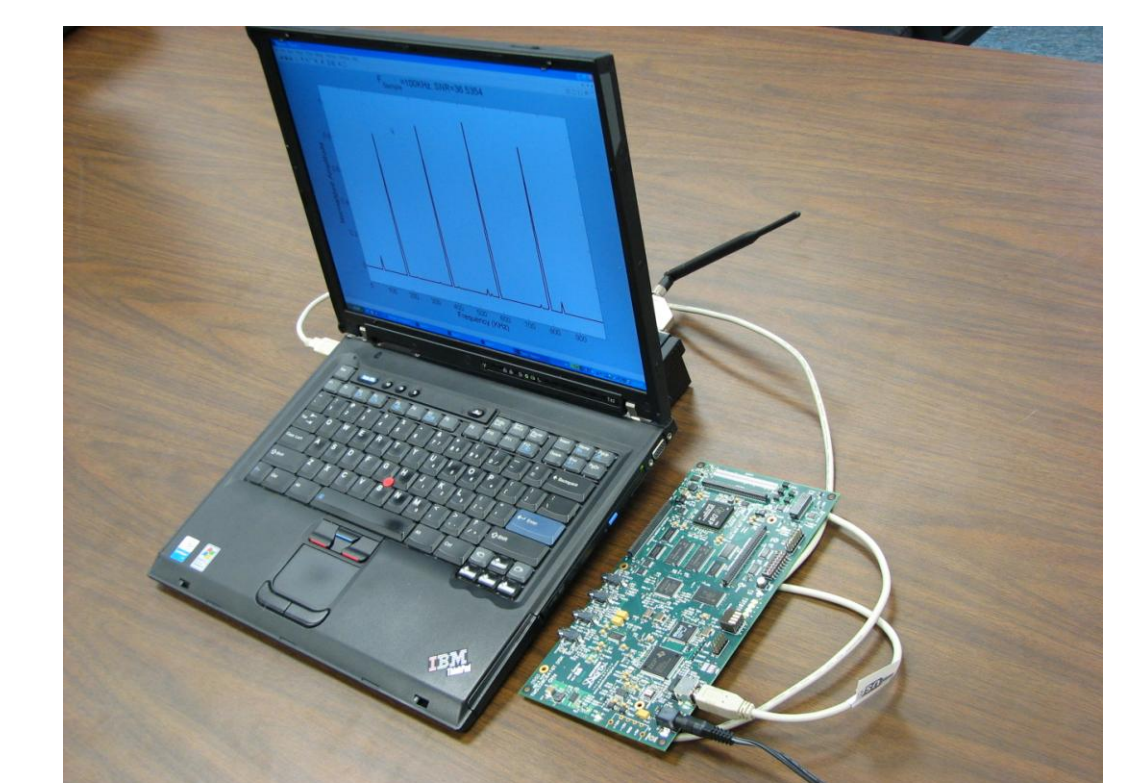


prototype PCB implementation using ultrawideband hardware

acquisition



reconstruction



Smashed Filter

- Random measurements are **information scalable** – reconstruction > estimation > classification > detection
- Smashed filter**: compressed matched filter – exploits random measurements/sketches and manifold structure of many classification problems

Three image classes: tank, bus, and SUV

