

# A Compressive Introduction to Compressive Sensing

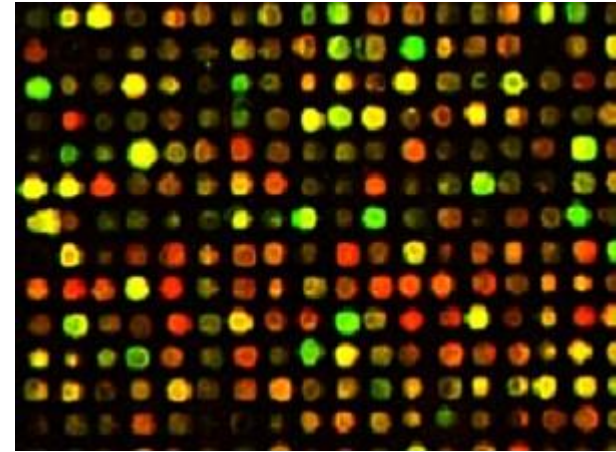
*Mark A. Davenport*

Georgia Institute of Technology

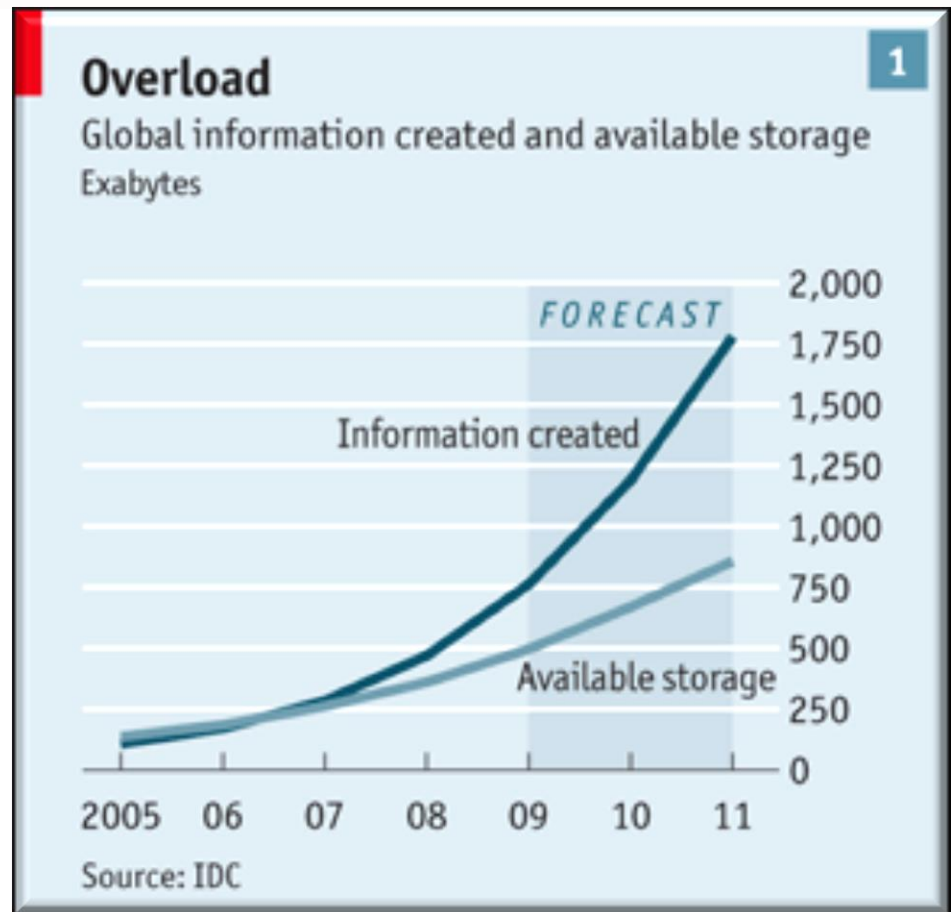
School of Electrical and Computer Engineering



# Sensor Explosion




# Data Deluge



# 2012 Math Awareness Month

## Mathematics, Statistics, and the Data Deluge



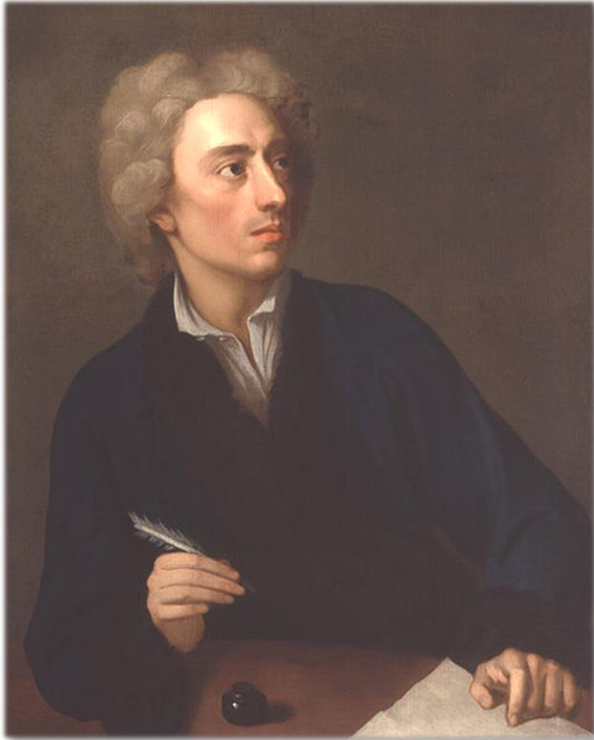
**WHAT WOULD YOU DO WITH ALL THIS DATA?**

Mathematics and statistics provide the tools to understand ever-increasing amounts of data. To learn more, visit the Mathematics Awareness Month website and enter for a chance to win an iTunes gift card at [www.mathaware.org](http://www.mathaware.org).

**Mathematics, Statistics, and the Data Deluge**  
**MATHEMATICS AWARENESS MONTH**

Sponsored by the Joint Policy Board for Mathematics—American Mathematical Society, American Statistical Association, Mathematical Association of America, Society for Industrial and Applied Mathematics

# Ye Olde Data Deluge

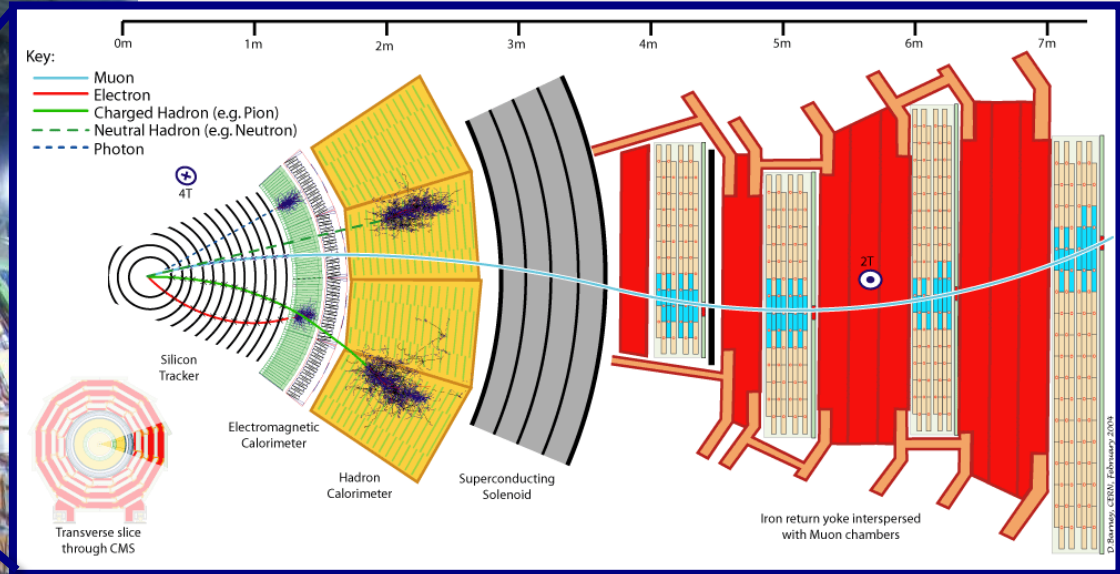
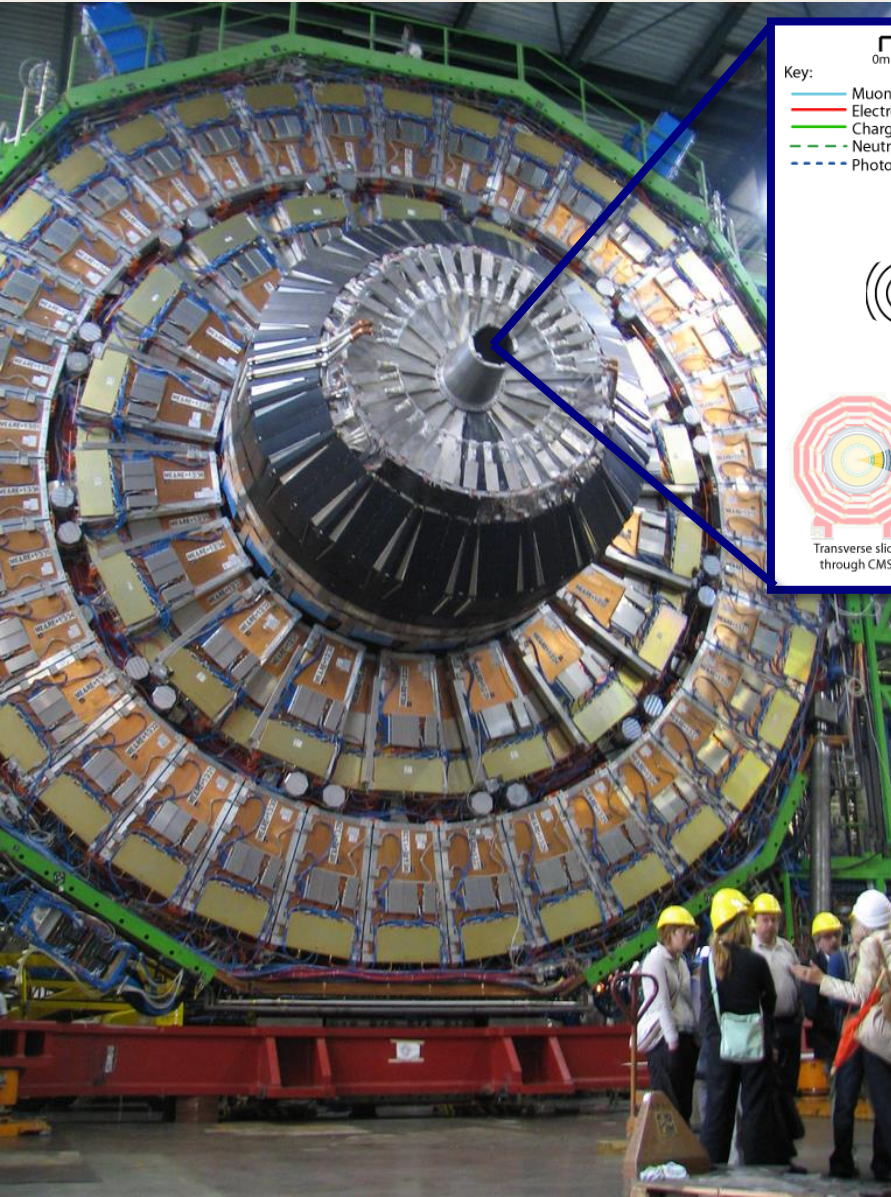


“Paper became so cheap, and printers so numerous, that a deluge of authors covered the land”

Alexander Pope, 1728



# Large Hadron Collider at CERN

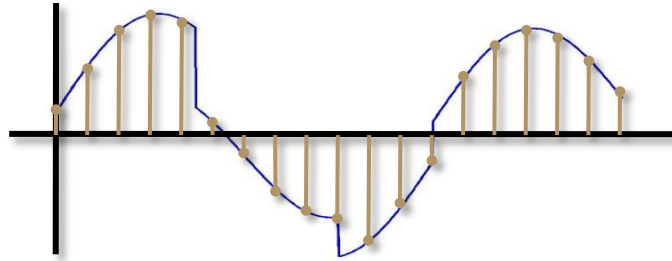


Compact Muon Solenoid detector

*320 terabits per second* raw data

Stop-gap: perform ad-hoc triage to 800 Gbps, recording only “interesting events”

# Digital Revolution



“If we sample a signal at twice its highest frequency, then we can recover it exactly.”

Whittaker-Nyquist-Kotelnikov-Shannon



# Data, Data Everywhere...

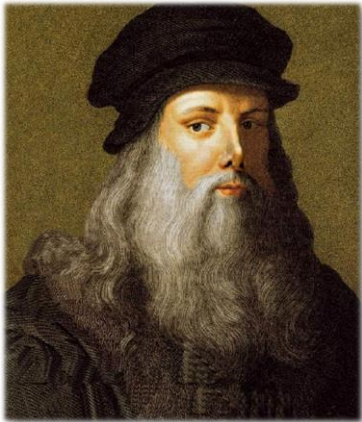
Do we *really* need so many samples?



Most *natural* signals have *simple* characterizations



# Simplicity Through History



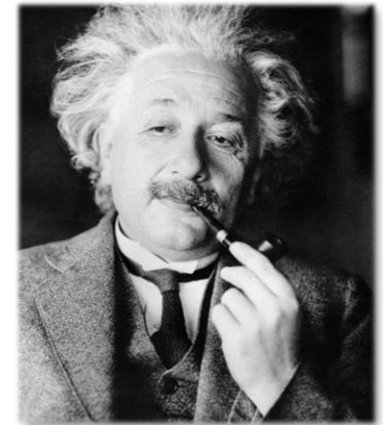
“Entities must not be multiplied unnecessarily”

-William of Occam



“Simplicity is the ultimate sophistication”

-Leonardo da Vinci

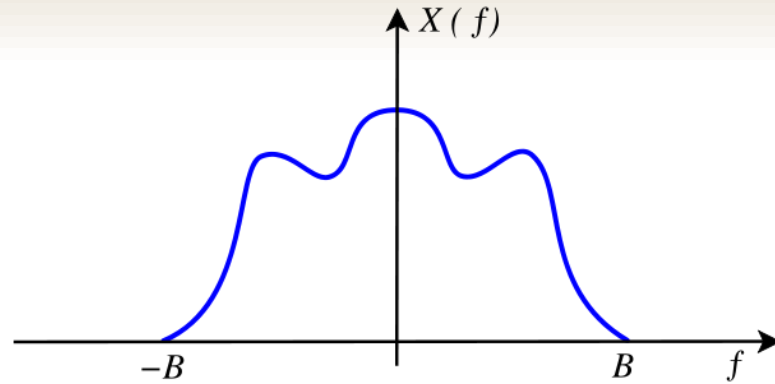


“Make everything as simple as possible, but not simpler”

-Albert Einstein

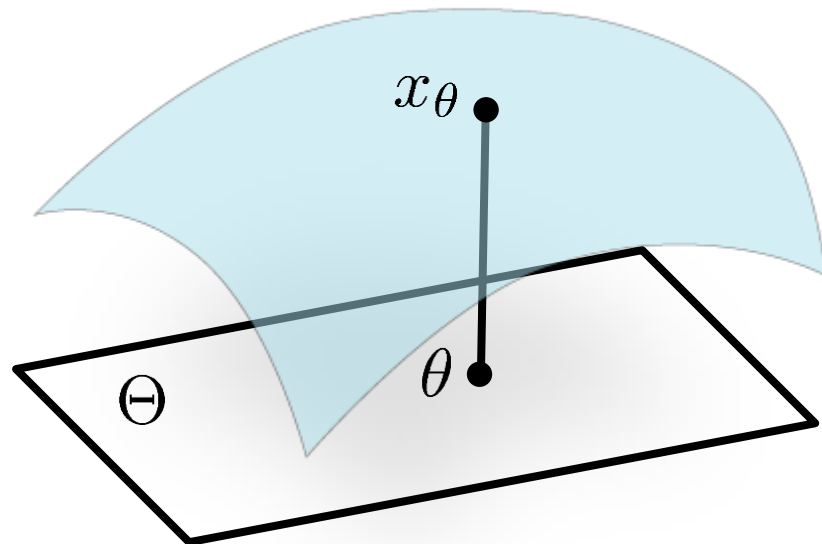
# Simple Signals

- Bandlimited signals



- Parametric signals

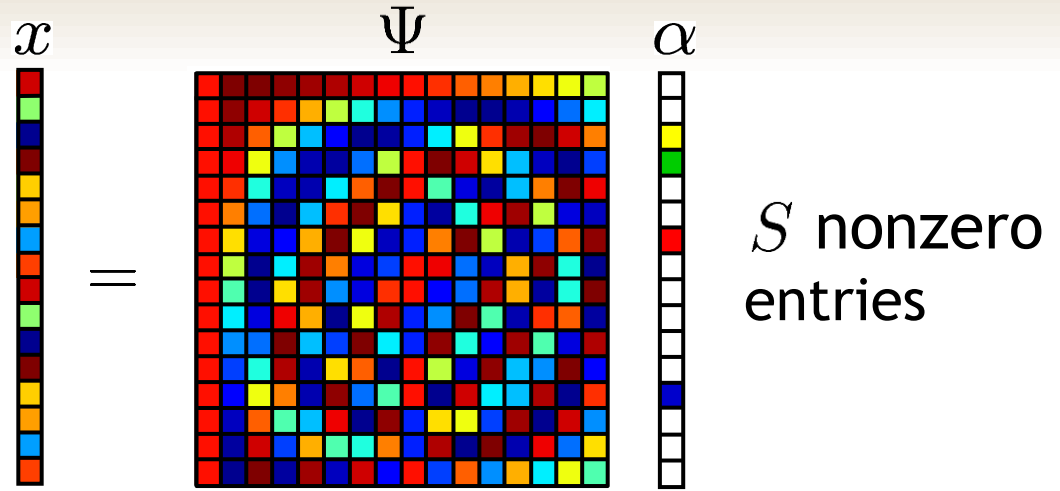
$\mathbb{R}^N$



- Sparse signals

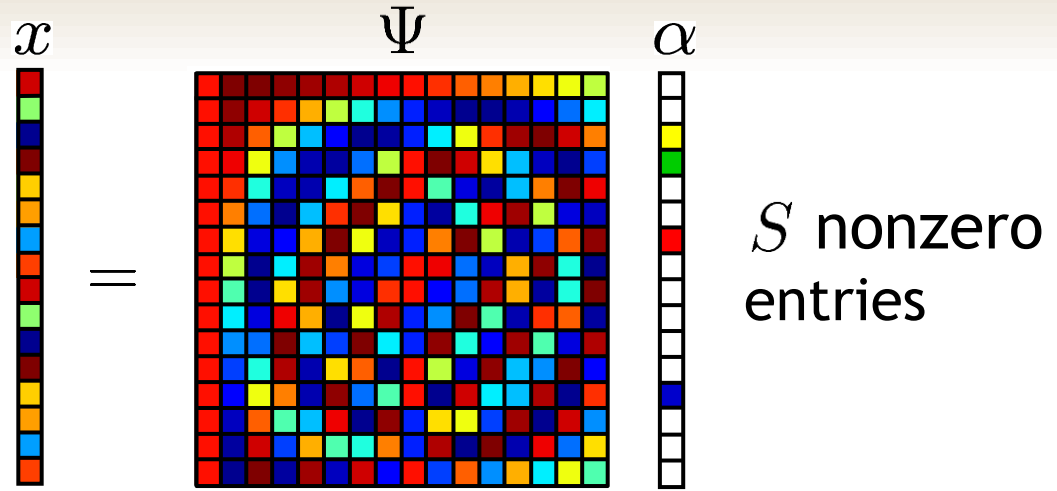
# Sparsity

$$\begin{aligned}x &= \sum_{j=1}^N \alpha_j \psi_j \\ &= \Psi \alpha\end{aligned}$$

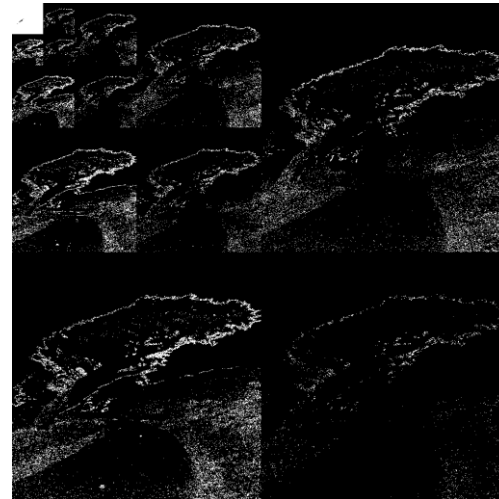


# Sparsity

$$x = \sum_{j=1}^N \alpha_j \psi_j$$
$$= \Psi \alpha$$



$N$   
pixels

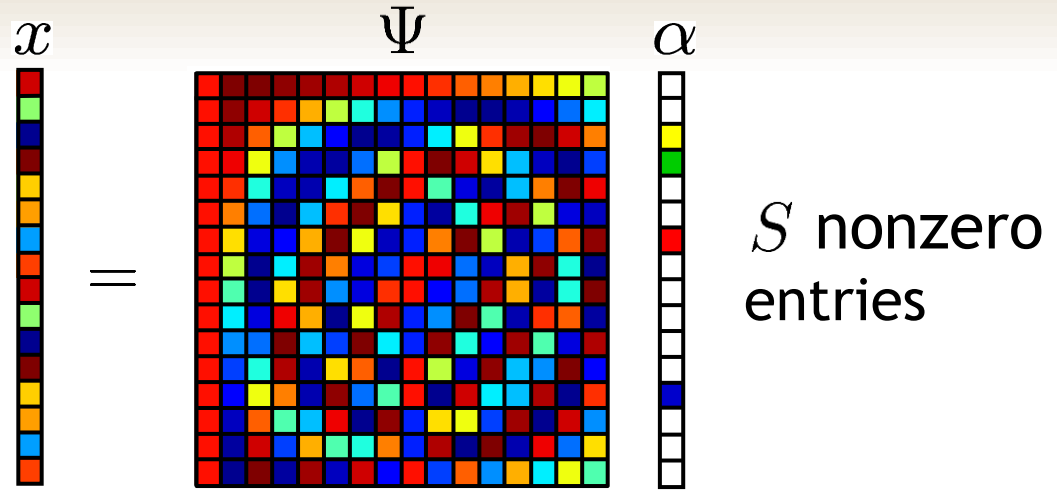


$S \ll N$   
large  
wavelet  
coefficients

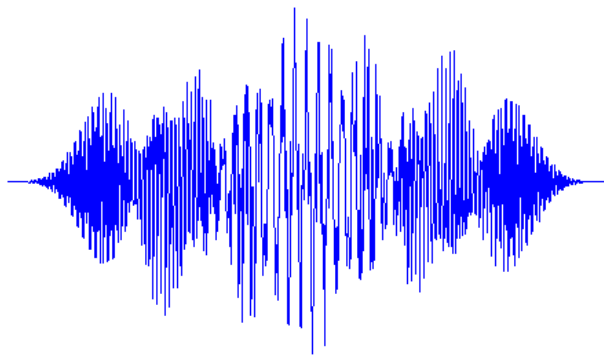


# Sparsity

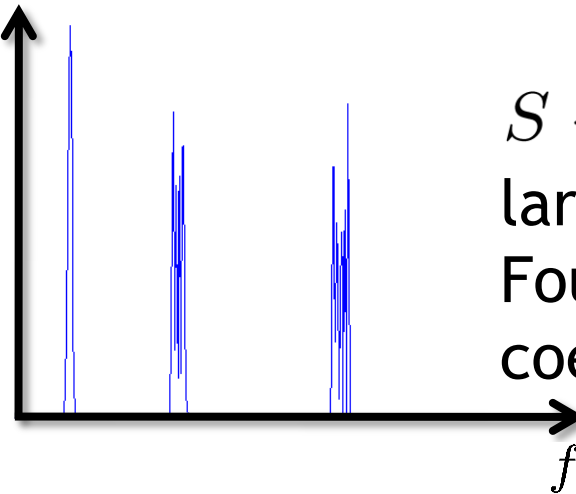
$$x = \sum_{j=1}^N \alpha_j \psi_j$$
$$= \Psi \alpha$$



$N$  samples



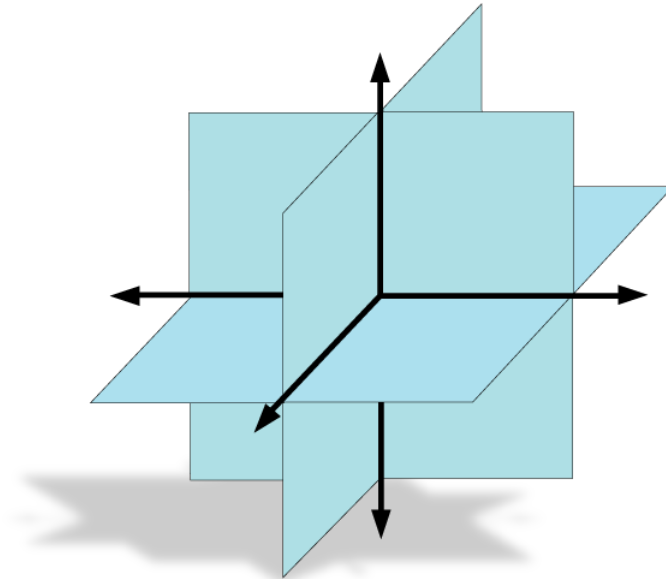
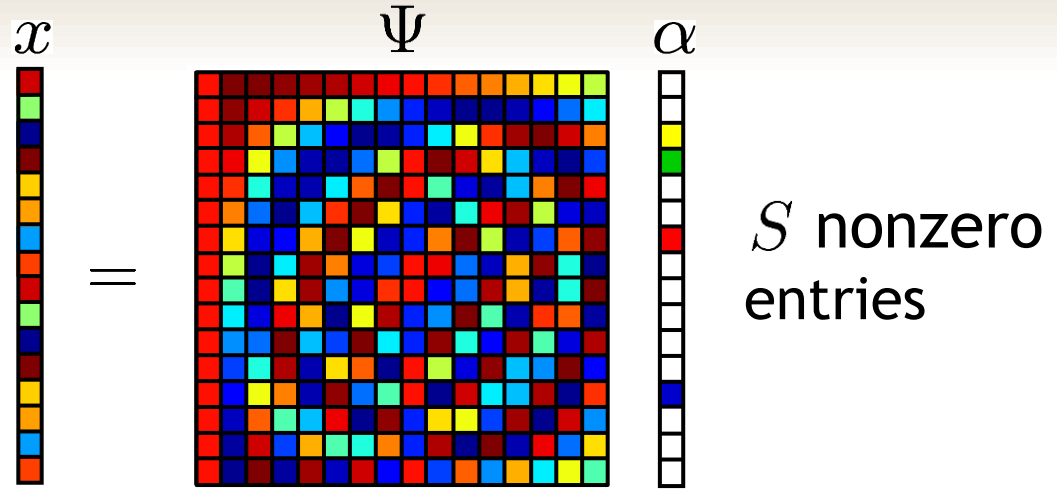
$X(f)$



$S \ll N$   
large  
Fourier  
coefficients

# Sparsity

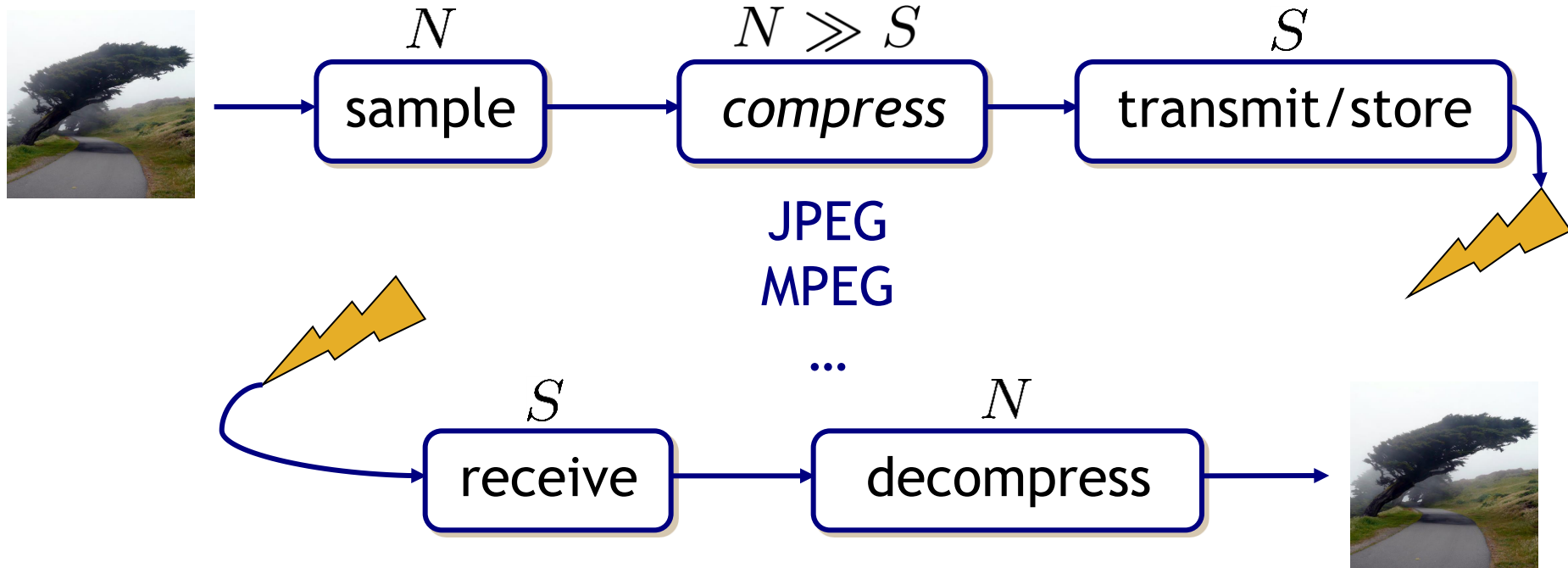
$$x = \sum_{j=1}^N \alpha_j \psi_j$$
$$= \Psi \alpha$$



# Sample-Then-Compress Paradigm

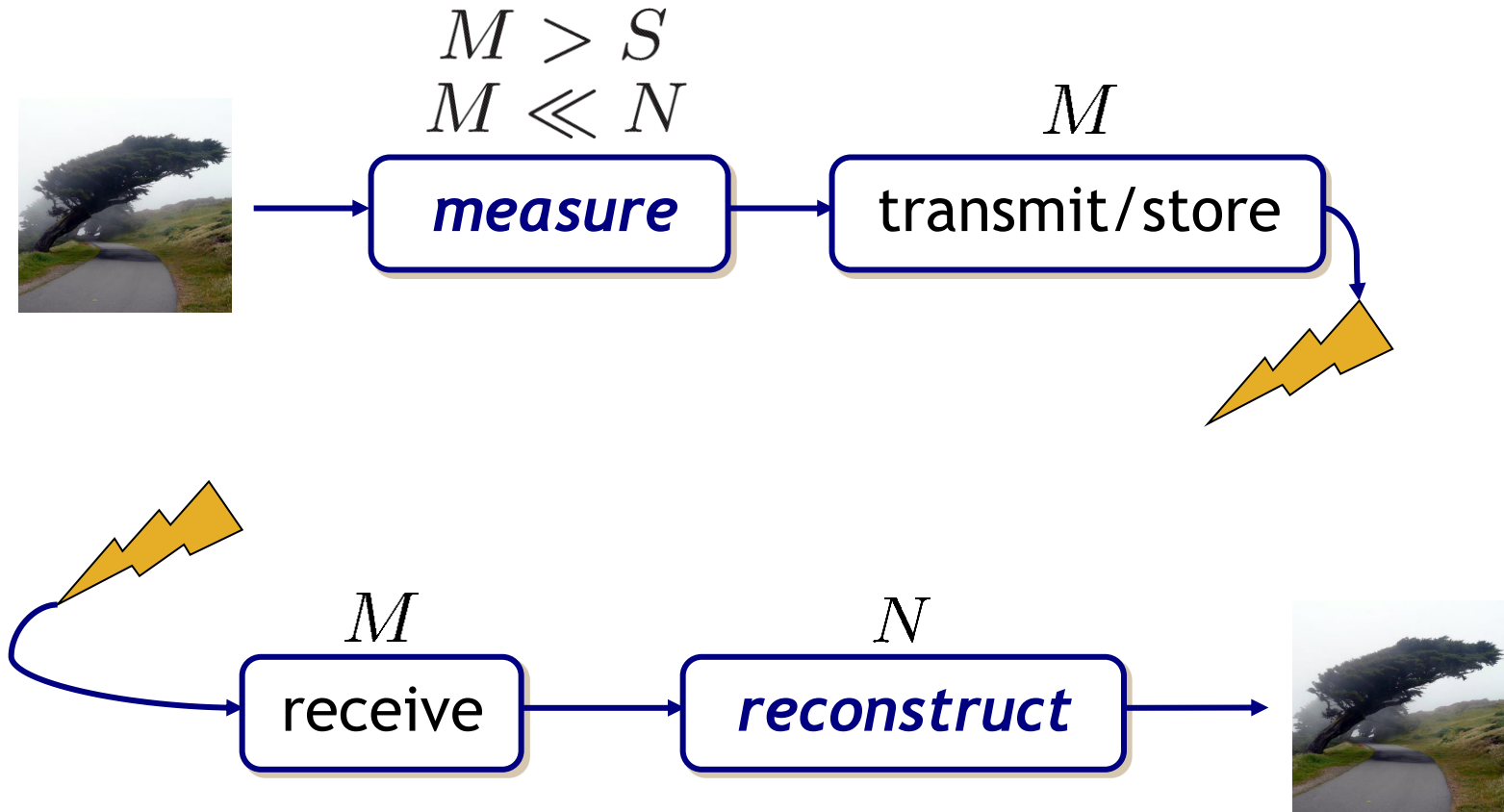
Standard paradigm for digital data acquisition

- *sample* data
- *compress* samples



Sample-then-compress paradigm is *wasteful*

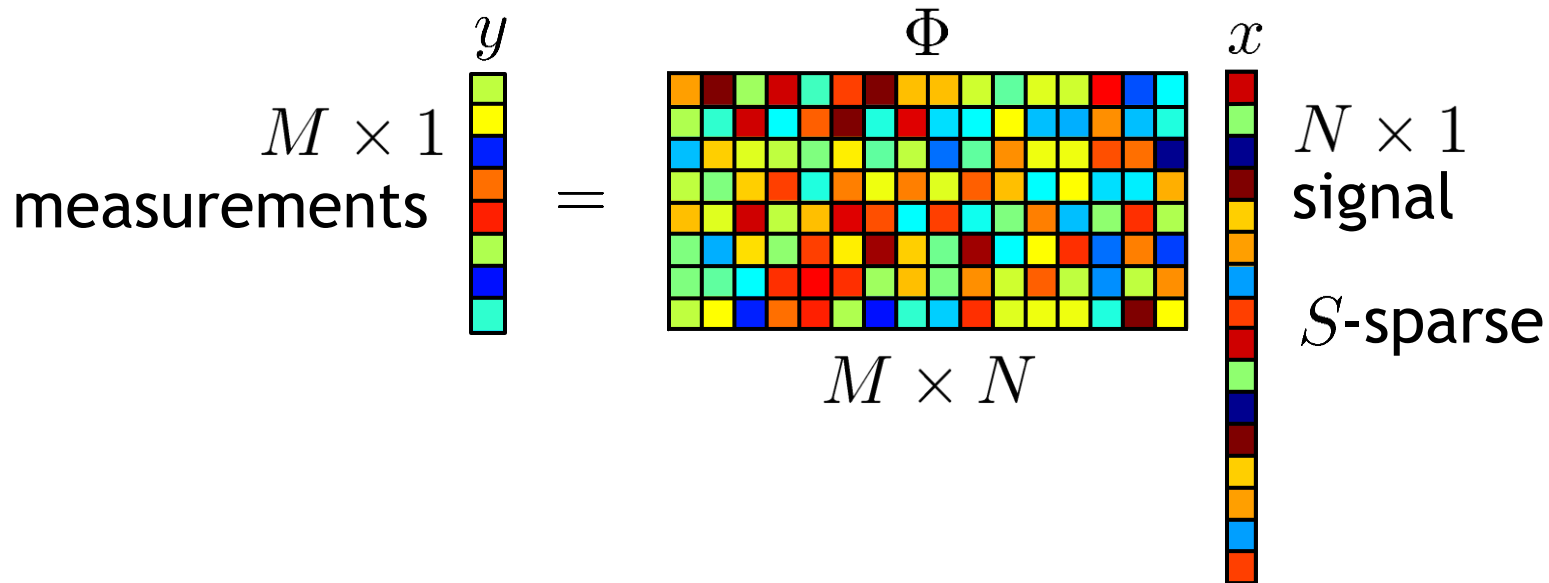
# Compressive Sensing





# Compressive Sensing

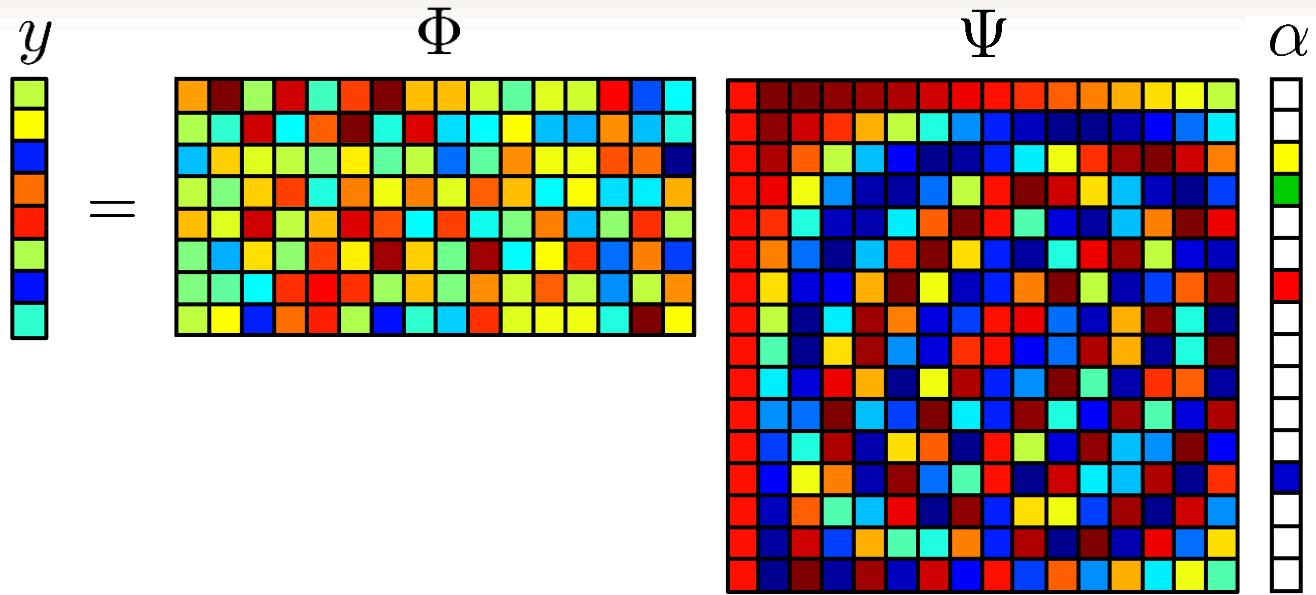
Replace samples with general *linear measurements*



Core challenges:

- how to design  $\Phi$ ?
- how to recover  $x$ ?

# Sparse Signal Recovery



# Sparse Signal Recovery

The diagram illustrates the equation  $y = \tilde{\Phi} \alpha$ . On the left, the vector  $y$  is represented by a vertical column of 6 colored blocks: light green, yellow, blue, orange, red, and cyan. In the center, the matrix  $\tilde{\Phi}$  is a 6x12 grid of colored blocks. On the right, the vector  $\alpha$  is a vertical column of 12 white blocks, with a yellow block at the 2nd position, a green block at the 3rd position, a red block at the 7th position, and a blue block at the 10th position.

System of  $M$  equations with  $N$  unknowns

All but  $S$  of the unknowns are zero

**Goal:** Determine which entries are nonzero,  
then estimate their values

# Sparse Signal Recovery

given  $y = \Phi x$   
find  $x$

*does not lead  
to sparse  
solutions*

$$\longrightarrow \hat{x} = \arg \min_{x \in \mathbb{R}^N} \sum_{j=1}^N x_j^2 \quad \text{s.t.} \quad y = \Phi x$$

*nonconvex  
NP-Hard*

$$\longrightarrow \hat{x} = \arg \min_{x \in \mathbb{R}^N} \sum_{j=1}^N \tilde{x}_j \quad \text{s.t.} \quad y = \Phi x$$
$$\tilde{x}_j = \begin{cases} 1 & \text{if } x_j \neq 0 \\ 0 & \text{otherwise} \end{cases}$$

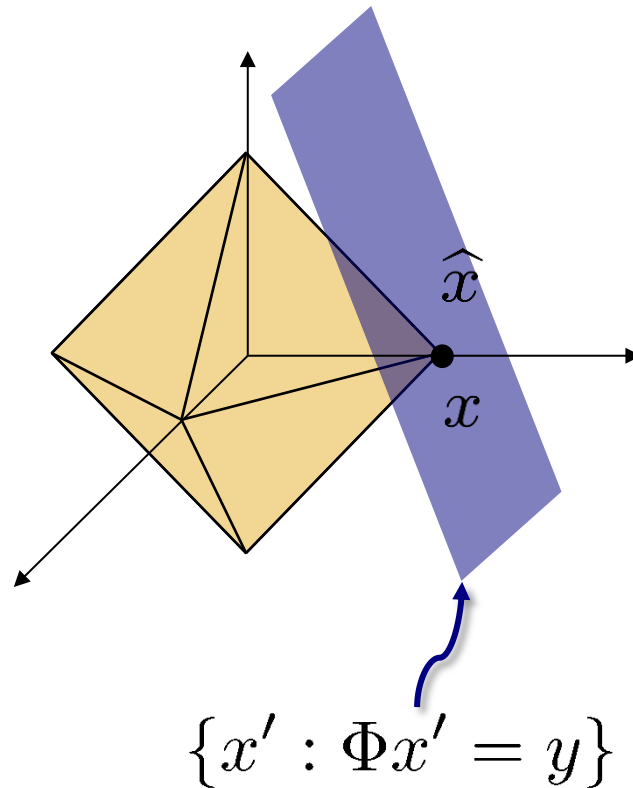
*convex  
linear program*

$$\longrightarrow \hat{x} = \arg \min_{x \in \mathbb{R}^N} \sum_{j=1}^N |x_j| \quad \text{s.t.} \quad y = \Phi x$$

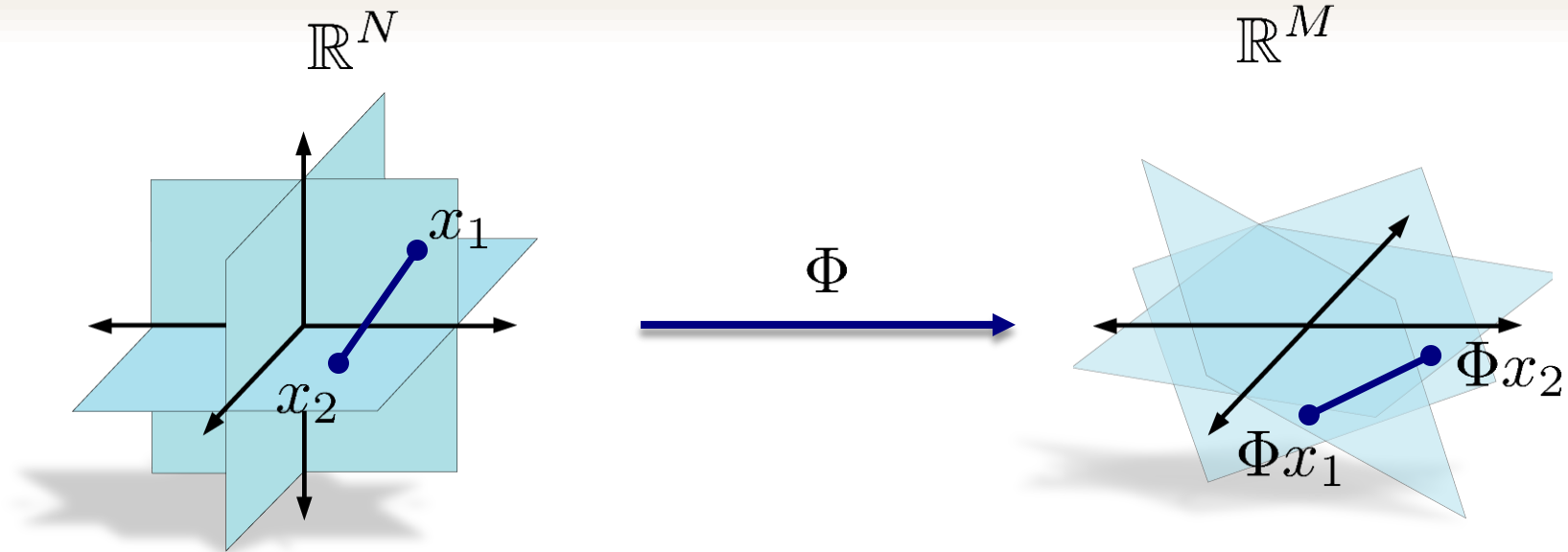


# Why $\ell_1$ -Minimization Might Work

$$\begin{aligned} \hat{x} &= \arg \min_{x \in \mathbb{R}^N} \|x\|_1 \\ \text{s.t. } & y = \Phi x \end{aligned}$$



# Restricted Isometry Property (RIP)

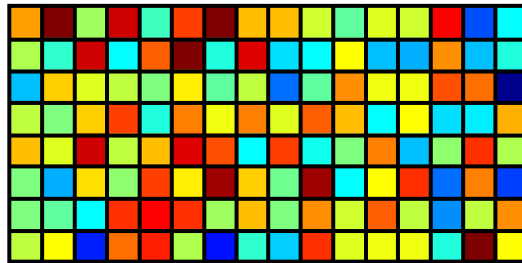


$$\|\Phi x_1 - \Phi x_2\|_2^2 \approx \|x_1 - x_2\|_2^2 \quad \text{for all sparse } x_1, x_2$$

# How to Get an RIP Matrix

Choose a *random matrix*

- fill out the entries of  $\Phi$  with i.i.d. samples from a sub-Gaussian distribution
- project onto a “random subspace”



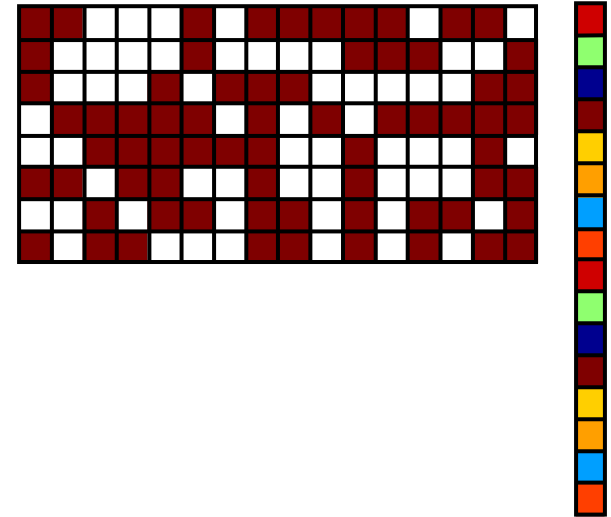
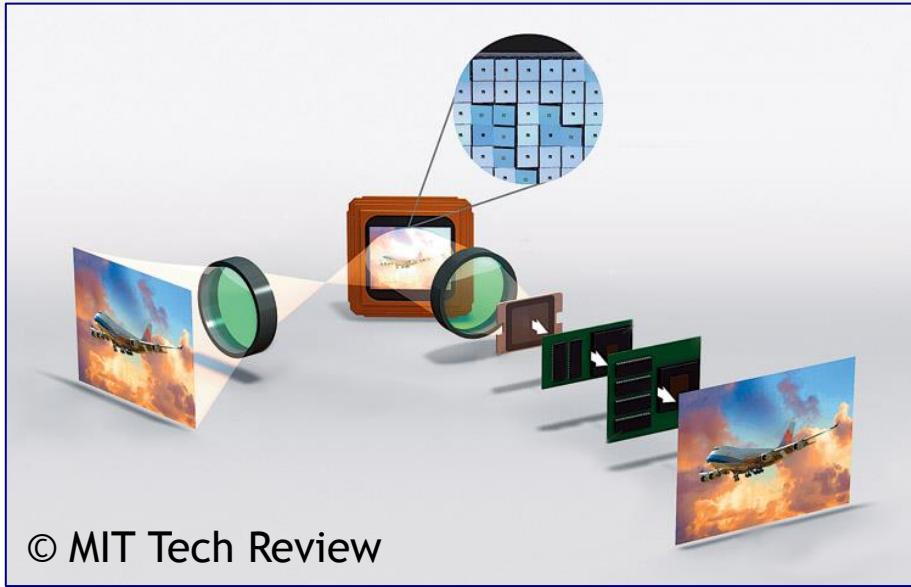
$$M = O(S \log(N/S)) \ll N$$

*Many more structured options are now available*

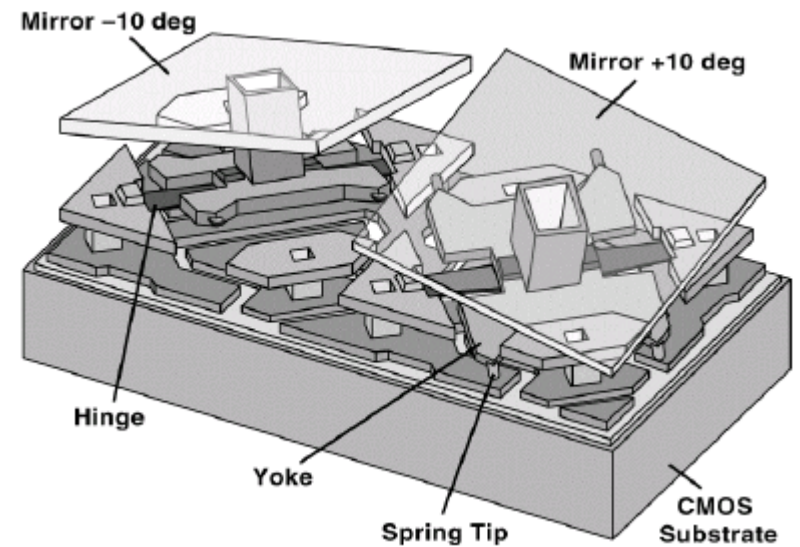
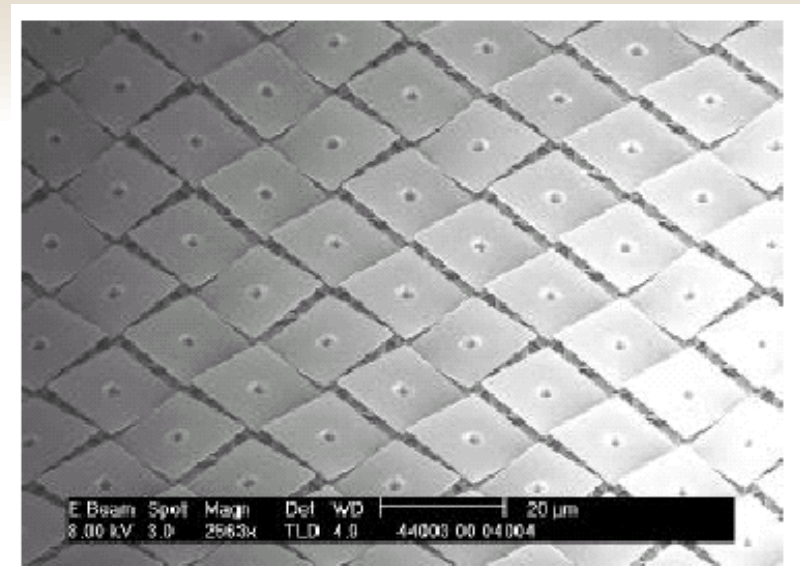
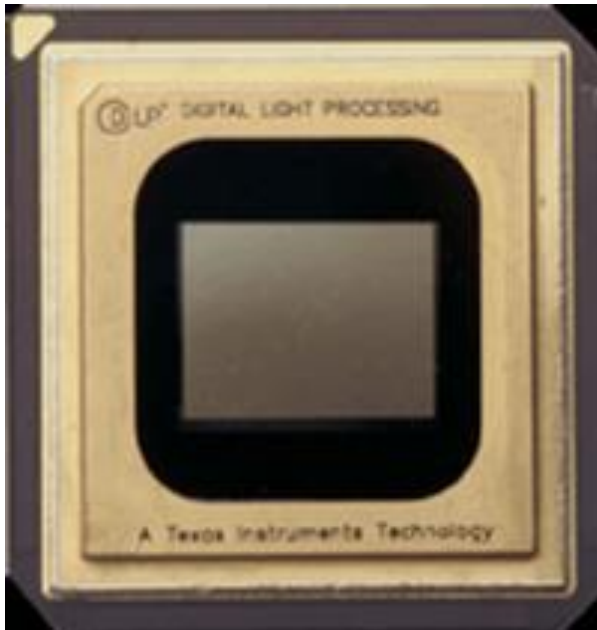
# Sparse Recovery Guarantees

- Optimization /  $\ell_1$  -minimization
- Greedy algorithms
  - matching pursuit
  - orthogonal matching pursuit (OMP)
  - Stagewise OMP (StOMP), regularized OMP (ROMP)
  - CoSaMP, Subspace Pursuit, IHT, ...
- If  $\Phi$  satisfies the RIP, then any of these algorithms can successfully recover  $x$

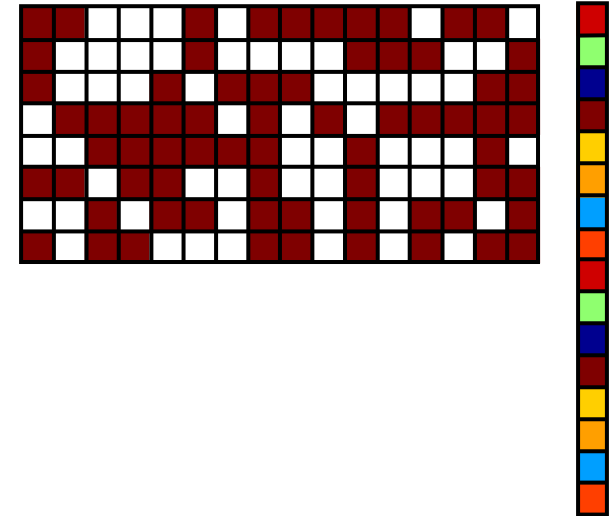
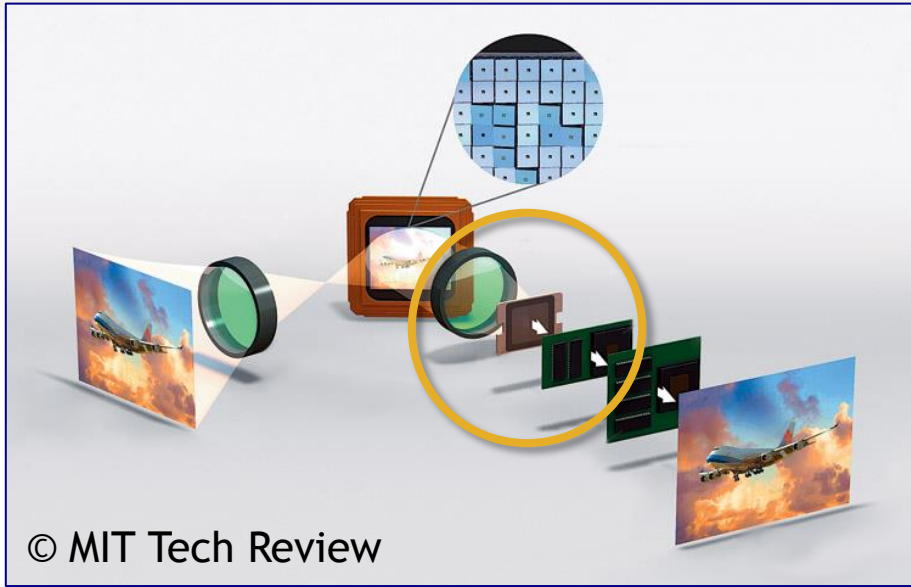
# “Single-Pixel Camera”



# TI Digital Micromirror Device



# “Single-Pixel Camera”



# Conclusions

- The theory of compressive sensing allows for new sensor designs, but requires new techniques for signal recovery
- Underdetermined systems of equations with sparse solutions arise in many other contexts
- “Simplicity” has many incarnations
  - sparsity
  - structured sparsity
  - finite rate of innovation, manifold, parametric models
  - low-rank matrices